

ISL8088

Dual 800mA Low Quiescent Current 2.25MHz High Efficiency Synchronous Buck Regulator

FN6858
Rev 2.00
May 26, 2011

The ISL8088 is a high efficiency, dual synchronous step-down DC/DC regulator that can deliver up to 800mA continuous output current per channel. The supply voltage range of 2.75V to 5.5V allows the use of a single Li+ cell, three NiMH cells or a regulated 5V input. The current mode control architecture enables very low duty cycle operation at high frequency with fast transient response and excellent loop stability. The ISL8088 operates at 2.25MHz switching frequency allowing the use of small, low cost inductors and capacitors. Each channel is optimized for generating an output voltage as low as 0.6V.

The ISL8088 has a user configurable mode of operation-forced PWM mode and PFM/PWM mode. The forced PWM mode operation reduces noise and RF interference while the PFM mode operation provides high efficiency by reducing switching losses at light loads. In PFM mode of operation, both channels draw a total quiescent current of only 30 μ A hence enabling high light load efficiency in order to maximize battery life.

The ISL8088 offers a 1ms Power-Good (PG) to monitor both output at power-up. When shutdown, ISL8088 discharges the outputs capacitor. Other features include internal digital soft-start, enable for power sequence, overcurrent protection, and thermal shutdown. The ISL8088 is offered in a 3mmx3mm 10 Ld DFN package with 1mm maximum height. The complete converter occupies less than 1.8cm² area.

Features

- Internal Current Mode Compensation
- 100% Maximum Duty Cycle for Lowest Dropout
- Selectable Forced PWM Mode and PFM Mode
- External Synchronization up to 4MHz
- Start-up with Pre-biased Output
- Soft-Stop Output Discharge During Disabled
- Internal Digital Soft-Start - 2ms
- Power-Good (PG) Output with 1ms Delay

Applications

- DC/DC POL Modules
- μ C/ μ P, FPGA and DSP Power
- Plug-in DC/DC Modules for Routers and Switchers
- Test and Measurement Systems
- Li-ion Battery Power Devices
- Bar Code Readers

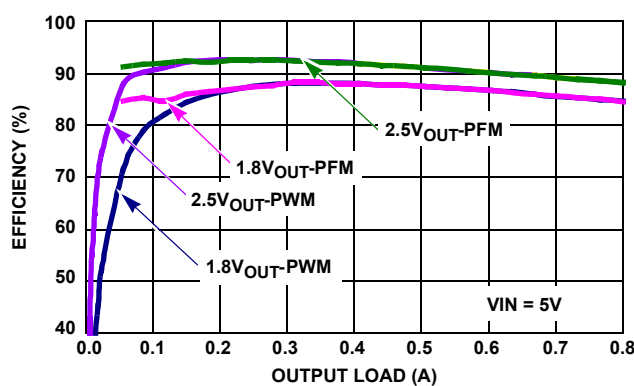
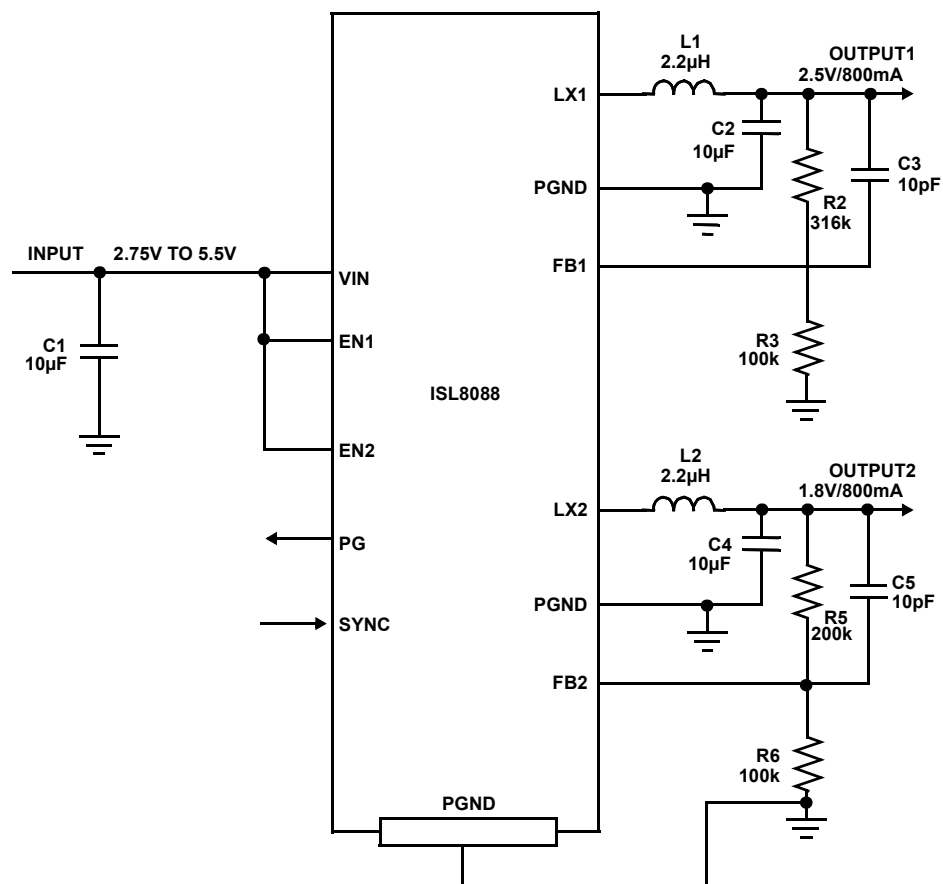
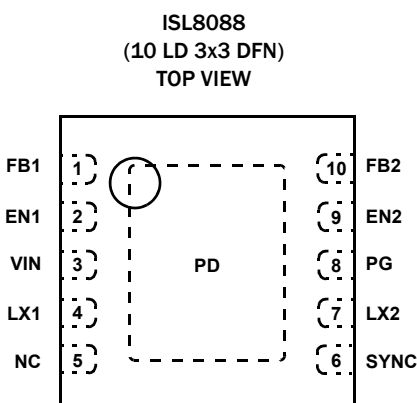


FIGURE 1. EFFICIENCY CHARACTERISTICS CURVE

Typical Application



Pin Configuration



Pin Descriptions

DFN	SYMBOL	DESCRIPTION
1	FB1	The feedback network of the Channel 1 regulator. FB1 is the negative input to the transconductance error amplifier. The output voltage is set by an external resistor divider connected to FB1. With a properly selected divider, the output voltage can be set to any voltage between the power rail (reduced by converter losses) and the 0.6V reference. There is an internal compensation to meet a typical application. In addition, the regulator power-good and undervoltage protection circuitry use FB1 to monitor the Channel 1 regulator output voltage.
2	EN1	Regulator Channel 1 enable pin. Enable the output, V_{OUT1} , when driven to high. Shutdown the V_{OUT1} and discharge output capacitor when driven to low. Do not leave this pin floating.
3	VIN	Input supply voltage. Connect 10 μ F ceramic capacitor to power ground.
4	LX1	Switching node connection for Channel 1. Connect to one terminal of inductor for V_{OUT1} .
5	NC	Recommended to connect this pin to the exposed pad.
6	SYNC	Mode Selection pin. Connect to logic high or input voltage VIN for PFM mode; connect to logic low or ground for forced PWM mode. Connect to an external function generator for Synchronization, and negative edge trigger. Do not leave this pin floating.
7	LX2	Switching node connection for Channel 2. Connect to one terminal of inductor for V_{OUT2} .
8	PG	1ms timer output. At power-up or EN_H, this output is a 1ms delayed Power-Good signal for both the V_{OUT1} and V_{OUT2} voltages. There is an internal 1M Ω pull-up resistor.
9	EN2	Regulator Channel 2 enable pin. Enable the output, V_{OUT2} , when driven to high. Shutdown the V_{OUT2} and discharge output capacitor when driven to low. Do not leave this pin floating.
10	FB2	The feedback network of the Channel 2 regulator. FB2 is the negative input to the transconductance error amplifier. The output voltage is set by an external resistor divider connected to FB2. With a properly selected divider, the output voltage can be set to any voltage between the power-rail (reduced by converter losses) and the 0.6V reference. There is an internal compensation to meet a typical application. In addition, the regulator power-good and undervoltage protection circuitry use FB2 to monitor the Channel 2 regulator output voltage.
-	PD	The exposed pad must be connected to PGND for proper electrical performance. Add as much vias as possible for optimal thermal performance.

Ordering Information

PART NUMBER (Notes 1, 2, 3)	PART MARKING	TEMP. RANGE (°C)	PACKAGE (Pb-Free)	PKG. DWG. #
ISL8088IRZ	8088	-40 to +85	10 Ld 3x3 DFN	L10.3x3C

NOTES:

1. Add "-T*" suffix for tape and reel. Please refer to [TB347](#) for details on reel specifications.
2. These Intersil Pb-free plastic packaged products employ special Pb-free material sets, molding compounds/die attach materials, and 100% matte tin plate plus anneal (e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations). Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.
3. For Moisture Sensitivity Level (MSL), please see device information page for [ISL8088](#). For more information on MSL please see techbrief [TB363](#).

Absolute Maximum Ratings (Reference to GND)

Supply Voltage (V_{IN})	-0.3V to 6.5V
V_{IN}	-0.3V to 7V (20ms)
EN1, EN2, PG, SYNC	-0.3V to $V_{IN} + 0.3V$
LX1, LX2	-1.5V to 6.5V
LX1, LX2	-1.5V (100ns)
	-0.3V (DC) to 7V (20ms)
FB1, FB2	-0.3V to 2.7V
ESD Rating	
Human Body Model	3kV
Machine Model	300V

Thermal Information

Thermal Resistance (Typical)	θ_{JA} (°C/W)	θ_{JC} (°C/W)
10 Ld 3x3 DFN Package (Notes 4, 5)	49	4
Storage Temperature Range	-65°C to +150°C	
Pb-Free Reflow Profile	see link below	
	http://www.intersil.com/pbfree/Pb-FreeReflow.asp	

Recommended Operating Conditions

V_{IN} Supply Voltage Range	2.75V to 5.5V
Load Current Range Per Channel	0mA to 800mA
Ambient Temperature Range	-40°C to +85°C
Junction Temperature Range	-40°C to +125°C

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

NOTES:

- θ_{JA} is measured in free air with the component mounted on a high effective thermal conductivity test board with "direct attach" features. See Tech Brief TB379.
- For θ_{JC} , the "case temp" location is the center of the exposed metal pad on the package underside.

Electrical Specifications

Unless otherwise noted, all parameter limits are established over the recommended operating conditions:

$T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$, $V_{IN} = 2.75\text{V}$ to 5.5V , $\text{EN1} = \text{EN2} = V_{IN}$, $\text{SYNC} = 0\text{V}$, $L = 2.2\mu\text{H}$, $C1 = 10\mu\text{F}$, $C2 = C4 = 10\mu\text{F}$, $\text{IOUT1} = \text{IOUT2} = 0\text{A}$ to 800mA . (Typical values are at $T_A = +25^\circ\text{C}$, $V_{IN} = 3.6\text{V}$). **Boldface limits apply over the operating temperature range, -40°C to +85°C.**

PARAMETER	SYMBOL	TEST CONDITIONS	MIN (Note 6)	TYP	MAX (Note 6)	UNITS
INPUT SUPPLY						
V _{IN} Undervoltage Lockout Threshold	V _{UVLO}	Rising		2.5	2.75	V
		Falling	2.1	2.4		V
Quiescent Supply Current	I _{VIN}	SYNC = V _{IN} , EN1 = EN2 = V _{IN} , no load at the output and no switches switching. VFB1 = VFB2 = 0.7V		30	50	μA
		SYNC = GND, EN1 = EN2 = VIN, F _S = 2.25MHz, no load at the output		0.1	1	mA
Shut Down Supply Current	I _{SD}	V _{IN} = 5.5V, EN1 = EN2 = GND		6.5	12	μA
OUTPUT REGULATION						
FB1, FB2 Regulation Voltage	V _{FB_}		0.590	0.6	0.610	V
FB1, FB2 Bias Current	I _{FB_}	VFB = 0.55V		0.1		μA
Line Regulation		V _{IN} = V _O + 0.5V to 5.5V (minimal 2.75V, I _{OUT} = 0A)		0.2		%/V
Soft-Start Ramp Time Cycle				2		ms
OVERCURRENT PROTECTION						
Peak Overcurrent Limit	I _{pk1}		0.95	1.2	1.6	A
	I _{pk2}		0.95	1.2	1.6	A
Peak SKIP Limit	I _{skip1}	V _{IN} = 3.6V	180	250	360	mA
	I _{skip2}		180	250	360	mA
LX1, LX2						
P-Channel MOSFET ON-Resistance		V _{IN} = 5.5V, I _O = 200mA		180	350	mΩ
		V _{IN} = 2.75V, I _O = 200mA		320	450	mΩ
N-Channel MOSFET ON-Resistance		V _{IN} = 5.5V, I _O = 200mA		180	350	mΩ
		V _{IN} = 2.75V, I _O = 200mA		320	450	mΩ

Electrical Specifications Unless otherwise noted, all parameter limits are established over the recommended operating conditions: $T_A = -40^\circ\text{C}$ to $+85^\circ\text{C}$, $V_{IN} = 2.75\text{V}$ to 5.5V , $EN1 = EN2 = V_{IN}$, $SYNC = 0\text{V}$, $L = 2.2\mu\text{H}$, $C1 = 10\mu\text{F}$, $C2 = C4 = 10\mu\text{F}$, $I_{OUT1} = I_{OUT2} = 0\text{A}$ to 800mA . (Typical values are at $T_A = +25^\circ\text{C}$, $V_{IN} = 3.6\text{V}$). **Boldface limits apply over the operating temperature range, -40°C to $+85^\circ\text{C}$.** (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN (Note 6)	TYP	MAX (Note 6)	UNITS
LX_ Maximum Duty Cycle				100		%
PWM Switching Frequency	F_S		1.8	2.25	2.7	MHz
Synchronization Range			2.7		4	MHz
LX Minimum On-Time		$SYNC = 0$ (forced PWM mode)			100	ns
Soft Discharge Resistance	$R_{DIS_}$	$EN = LOW$	80	100	130	Ω
PG						
Output Low Voltage		Sinking 1mA, $V_{FB} = 0.5\text{V}$			0.3	V
PG Pull-up Resistor				1		M Ω
Internal P_{GOOD} Low Rising Threshold		Percentage of nominal regulation voltage	88	92	96	%
Internal P_{GOOD} Low Falling Threshold		Percentage of nominal regulation voltage	82	89	91	%
Delay Time (Rising Edge)				1		ms
Internal P_{GOOD} Delay Time (Falling Edge)				1	2	μs
EN1, EN2, SYNC						
Logic Input Low					0.4	V
Logic Input High			1.4			V
SYNC Logic Input Leakage Current	I_{SYNC}	Pulled up to 5.5V		0.1	1	μA
Enable Logic Input Leakage Current	$I_{EN_}$			0.1	1	μA
Thermal Shutdown				150		$^\circ\text{C}$
Thermal Shutdown Hysteresis				25		$^\circ\text{C}$

NOTE:

6. Parameters with MIN and/or MAX limits are 100% tested at $+25^\circ\text{C}$, unless otherwise specified. Temperature limits established by characterization and are not production tested.

Typical Operating Performance Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = 2.75\text{V to } 5.5\text{V}$, $EN = V_{IN}$, $L_1 = L_2 = 2.2\mu\text{H}$, $C_1 = 10\mu\text{F}$, $C_2 = C_4 = 10\mu\text{F}$, $V_{OUT1} = 2.5\text{V}$, $V_{OUT2} = 1.8\text{V}$, $I_{OUT1} = I_{OUT2} = 0\text{A to } 800\text{mA}$.

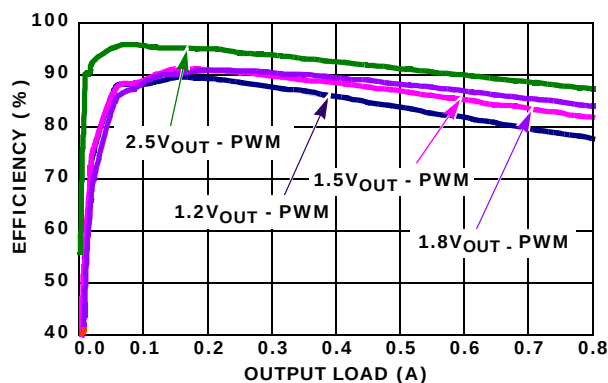


FIGURE 2. EFFICIENCY vs LOAD 2.25MHz 3.3VIN PWM

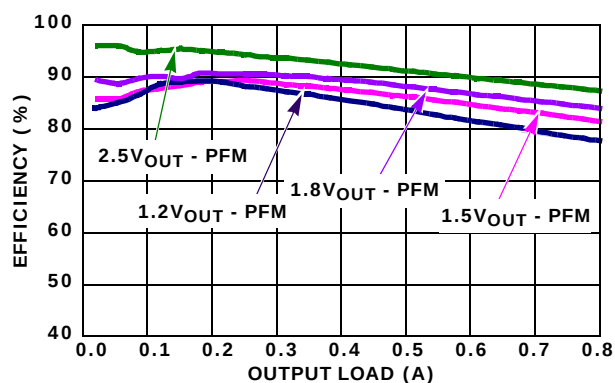


FIGURE 3. EFFICIENCY vs LOAD 2.25MHz 3.3VIN PFM

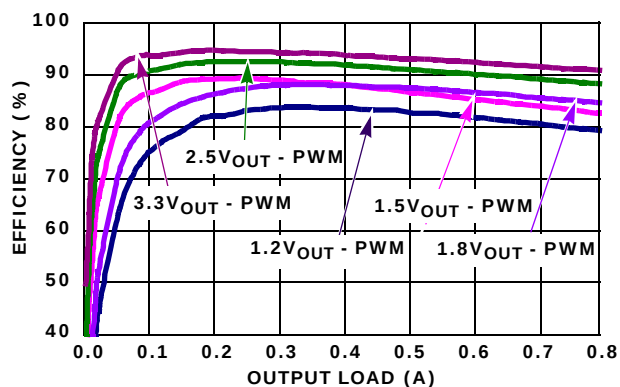


FIGURE 4. EFFICIENCY vs LOAD 2.25MHz 5VIN PWM

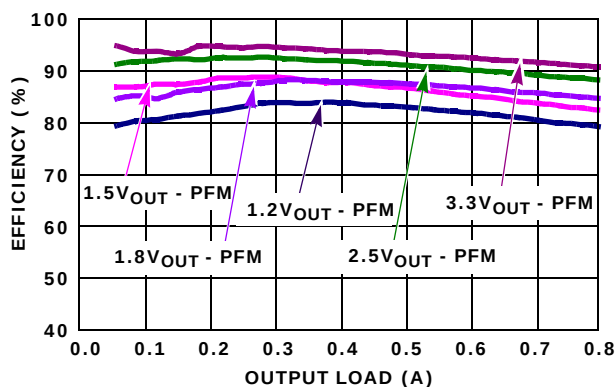


FIGURE 5. EFFICIENCY vs LOAD 2.25MHz 5VIN PFM

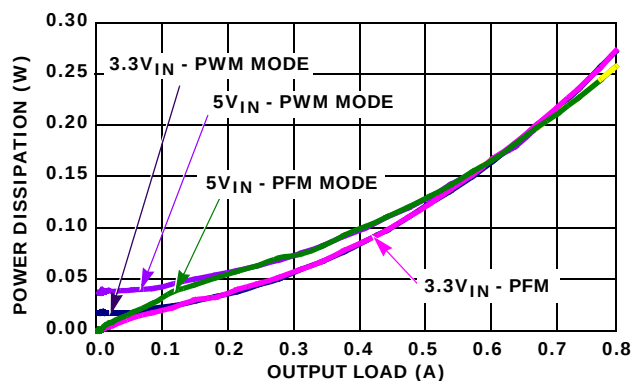
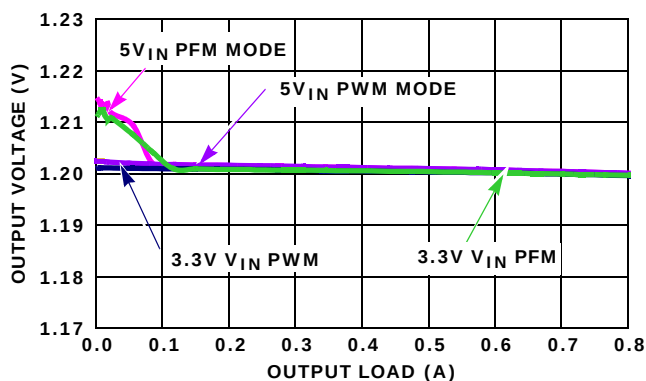


FIGURE 6. POWER DISSIPATION vs LOAD 2.25MHz 1.8VOUT PWM

FIGURE 7. V_{OUT} REGULATION vs LOAD 2.25MHz 1.2VOUT PFM

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = 2.75\text{V to } 5.5\text{V}$, $EN = V_{IN}$, $L_1 = L_2 = 2.2\mu\text{H}$, $C_1 = 10\mu\text{F}$, $C_2 = C_4 = 10\mu\text{F}$, $V_{OUT1} = 2.5\text{V}$, $V_{OUT2} = 1.8\text{V}$, $I_{OUT1} = I_{OUT2} = 0\text{A to } 800\text{mA}$. (Continued)

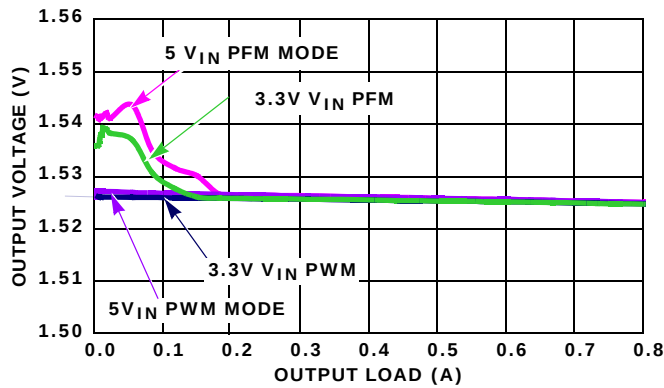


FIGURE 8. V_{OUT} REGULATION vs LOAD 2.25MHz 1.5V $_{OUT}$

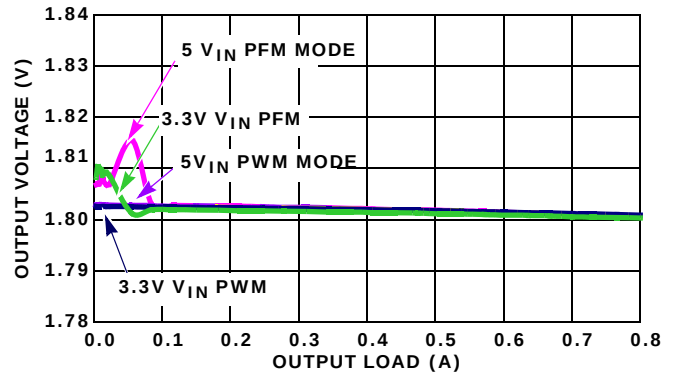


FIGURE 9. V_{OUT} REGULATION vs LOAD 2.25MHz 1.8V $_{OUT}$

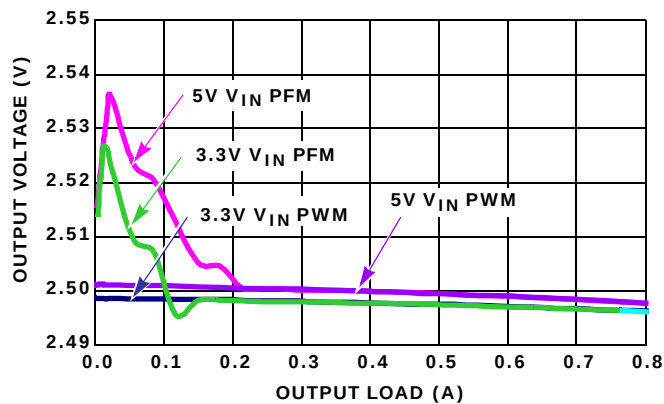


FIGURE 10. V_{OUT} REGULATION vs LOAD 2.25MHz 2.5V $_{OUT}$

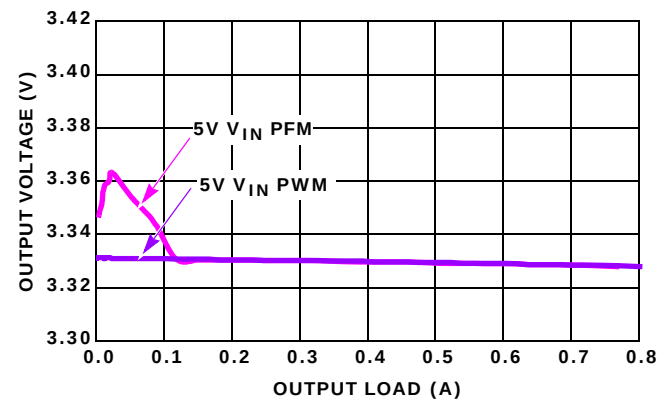


FIGURE 11. V_{OUT} REGULATION vs LOAD 2.25MHz 3.3V $_{OUT}$

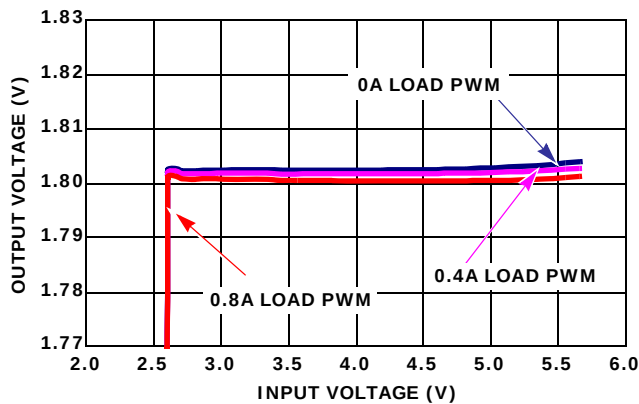


FIGURE 12. OUTPUT VOLTAGE REGULATION vs V_{IN} 1.8V $_{OUT}$ PWM MODE

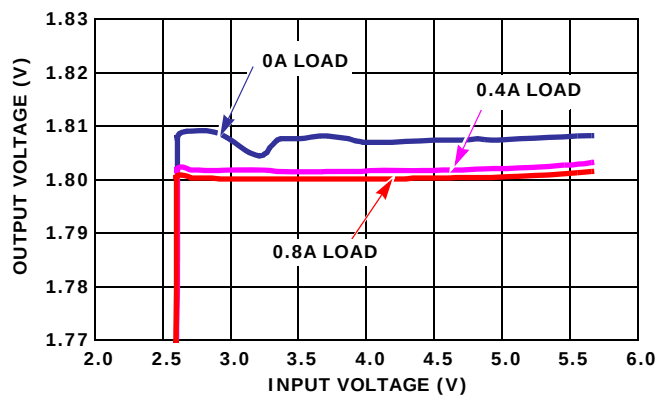


FIGURE 13. OUTPUT VOLTAGE REGULATION vs V_{IN} 1.8V $_{OUT}$ PFM MODE

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = 2.75\text{V to } 5.5\text{V}$, $EN = V_{IN}$, $L_1 = L_2 = 2.2\mu\text{H}$, $C_1 = 10\mu\text{F}$, $C_2 = C_4 = 10\mu\text{F}$, $V_{OUT1} = 2.5\text{V}$, $V_{OUT2} = 1.8\text{V}$, $I_{OUT1} = I_{OUT2} = 0\text{A to } 800\text{mA}$. (Continued)

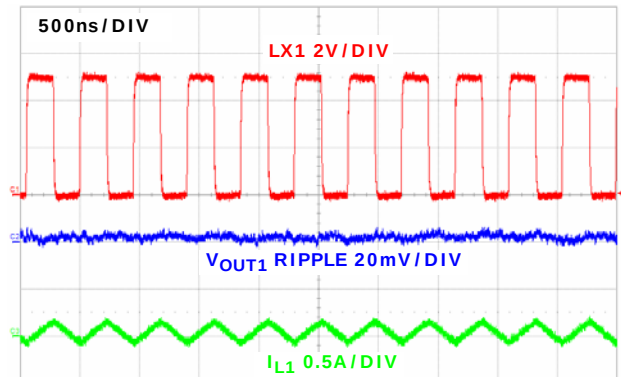


FIGURE 14. STEADY STATE OPERATION AT NO LOAD CHANNEL 1 (PWM)

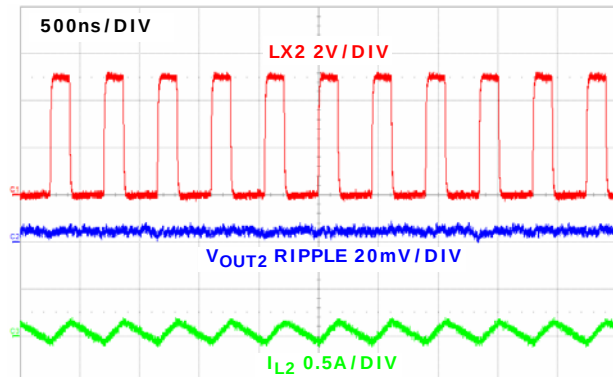


FIGURE 15. STEADY STATE OPERATION AT NO LOAD CHANNEL 2 (PWM)

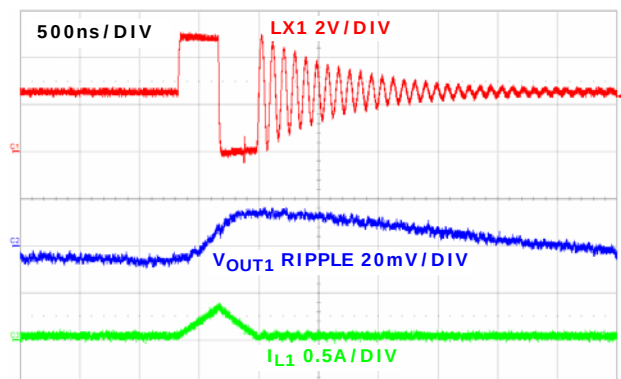


FIGURE 16. STEADY STATE OPERATION AT NO LOAD CHANNEL 1 (PFM)

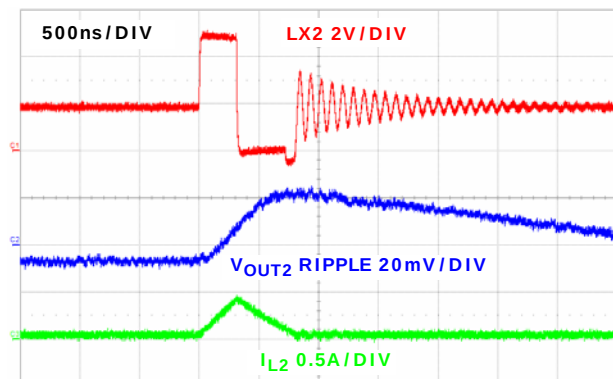


FIGURE 17. STEADY STATE OPERATION AT NO LOAD CHANNEL 2 (PFM)

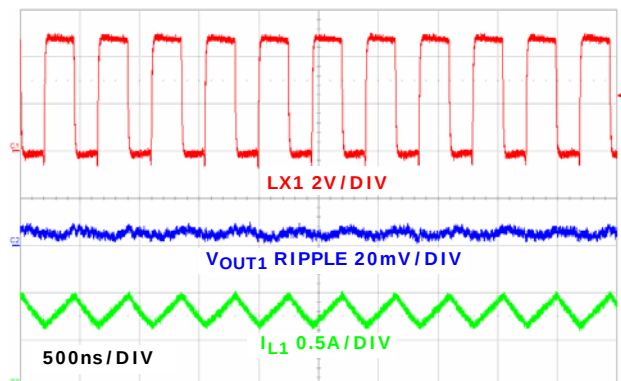


FIGURE 18. STEADY STATE OPERATION WITH FULL LOAD CHANNEL 1

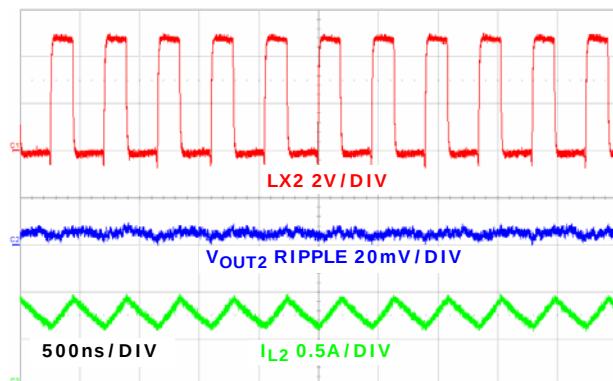


FIGURE 19. STEADY STATE OPERATION WITH FULL LOAD CHANNEL 2

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = 2.75\text{V to } 5.5\text{V}$, $EN = V_{IN}$, $L_1 = L_2 = 2.2\mu\text{H}$, $C_1 = 10\mu\text{F}$, $C_2 = C_4 = 10\mu\text{F}$, $V_{OUT1} = 2.5\text{V}$, $V_{OUT2} = 1.8\text{V}$, $I_{OUT1} = I_{OUT2} = 0\text{A to } 800\text{mA}$. (Continued)

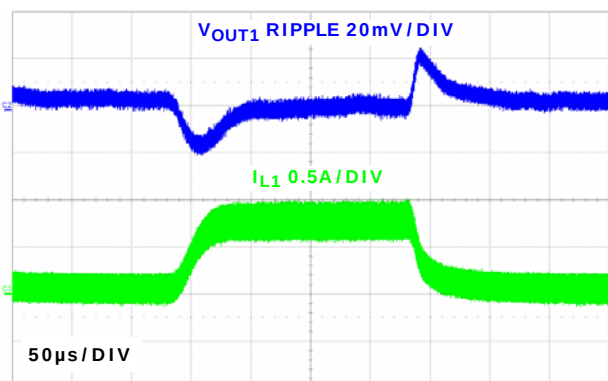


FIGURE 20. LOAD TRANSIENT CHANNEL 1 (PWM)

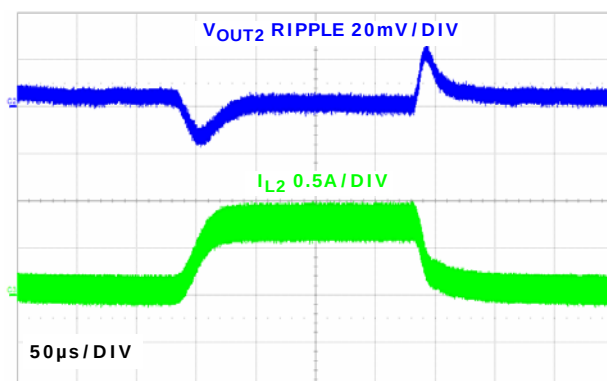


FIGURE 21. LOAD TRANSIENT CHANNEL 2 (PWM)

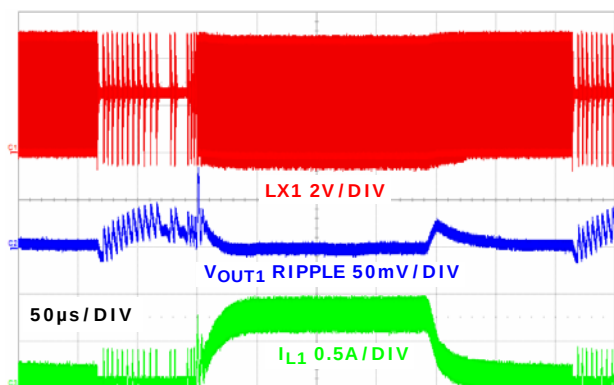


FIGURE 22. LOAD TRANSIENT CHANNEL 1 (PFM)

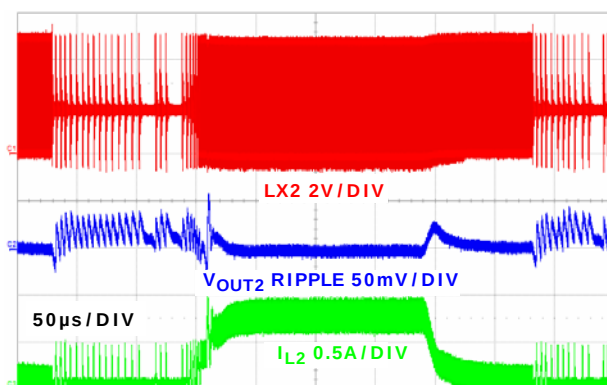


FIGURE 23. LOAD TRANSIENT CHANNEL 2 (PFM)

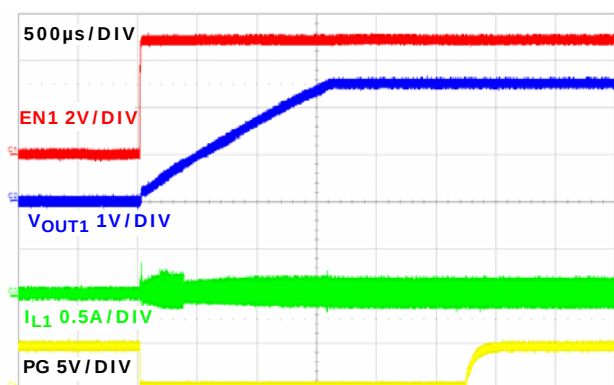


FIGURE 24. SOFT-START WITH NO LOAD CHANNEL 1 (PWM)

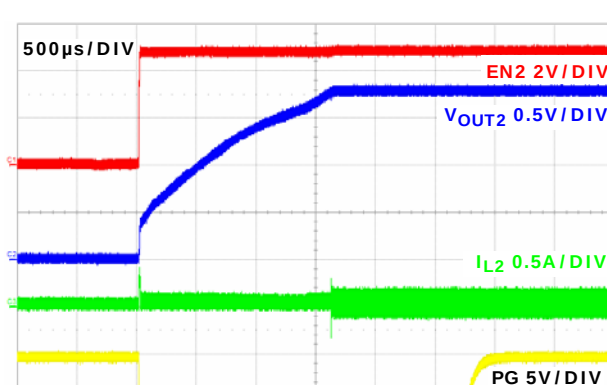


FIGURE 25. SOFT-START WITH NO LOAD CHANNEL 2 (PWM)

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = 2.75\text{V to } 5.5\text{V}$, $EN = V_{IN}$, $L_1 = L_2 = 2.2\mu\text{H}$, $C_1 = 10\mu\text{F}$, $C_2 = C_4 = 10\mu\text{F}$, $V_{OUT1} = 2.5\text{V}$, $V_{OUT2} = 1.8\text{V}$, $I_{OUT1} = I_{OUT2} = 0\text{A to } 800\text{mA}$. (Continued)

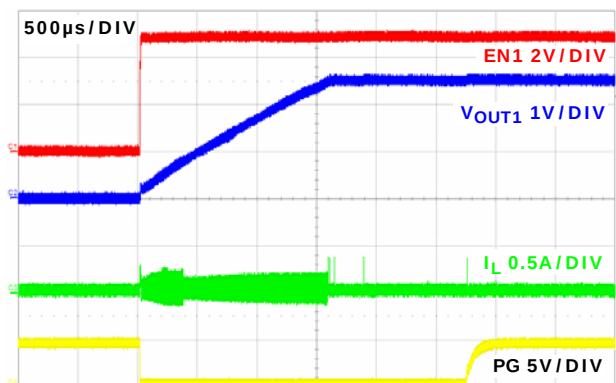


FIGURE 26. SOFT-START AT NO LOAD CHANNEL 1 (PFM)

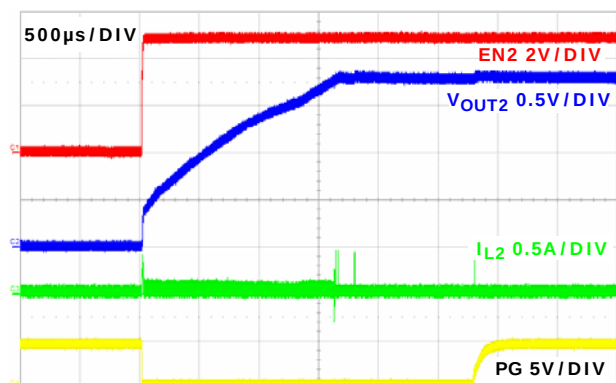


FIGURE 27. SOFT-START AT NO LOAD CHANNEL 2 (PFM)

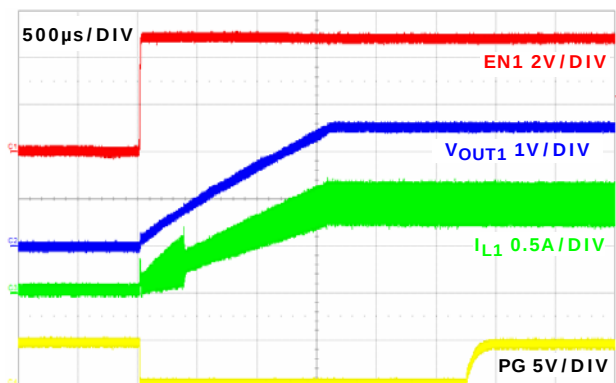


FIGURE 28. SOFT-START AT FULL LOAD CHANNEL 1

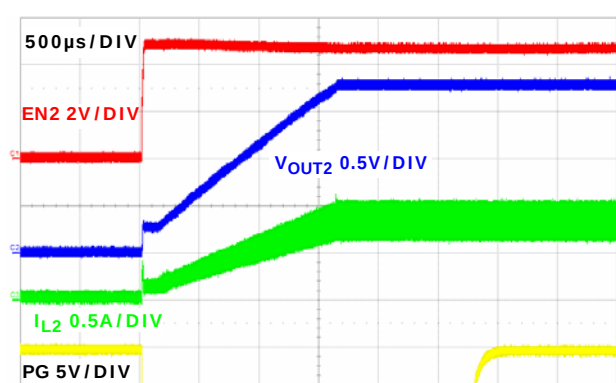


FIGURE 29. SOFT-START AT FULL LOAD CHANNEL 2

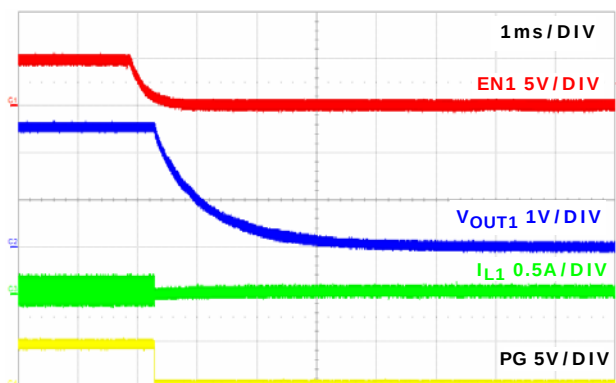


FIGURE 30. SOFT-DISCHARGE SHUTDOWN CHANNEL 1

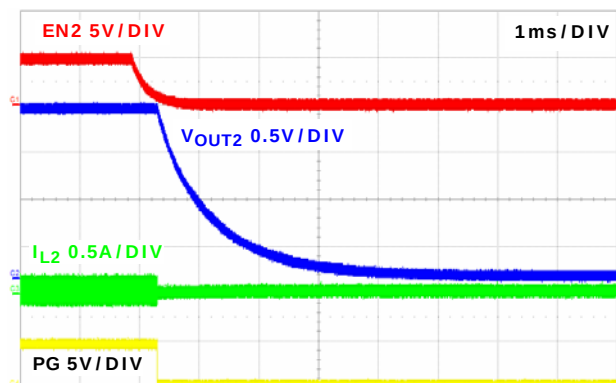


FIGURE 31. SOFT-DISCHARGE SHUTDOWN CHANNEL 2

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = 2.75\text{V to } 5.5\text{V}$, $EN = V_{IN}$, $L_1 = L_2 = 2.2\mu\text{H}$, $C_1 = 10\mu\text{F}$, $C_2 = C_4 = 10\mu\text{F}$, $V_{OUT1} = 2.5\text{V}$, $V_{OUT2} = 1.8\text{V}$, $I_{OUT1} = I_{OUT2} = 0\text{A to } 800\text{mA}$. (Continued)

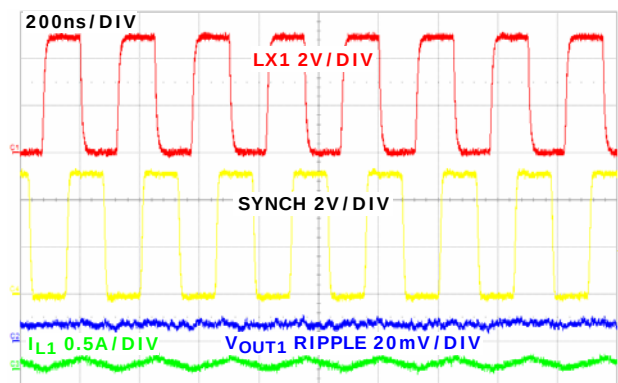


FIGURE 32. CH1 STEADY STATE OPERATION AT NO LOAD (PFM) WITH FREQUENCY = 4MHz

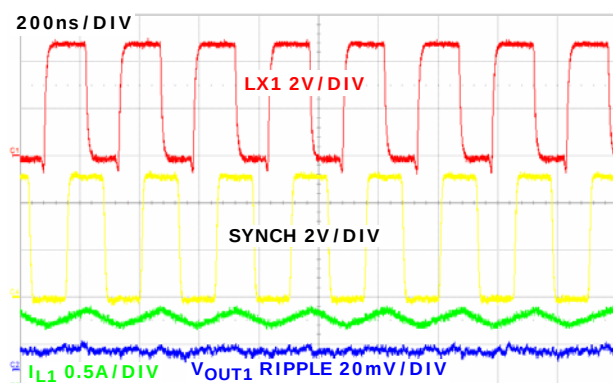


FIGURE 33. CH1 STEADY STATE OPERATION AT FULL LOAD (PFM) WITH FREQUENCY = 4MHz

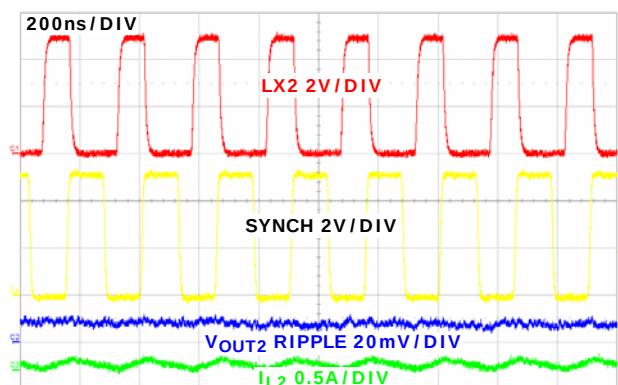


FIGURE 34. CH2 STEADY STATE OPERATION AT NO LOAD (PFM) WITH FREQUENCY = 4MHz

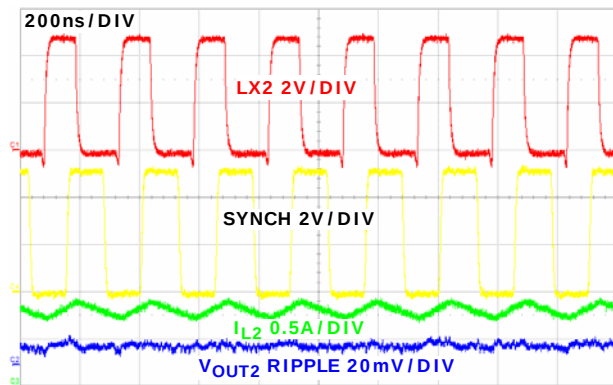


FIGURE 35. CH2 STEADY STATE OPERATION AT FULL LOAD (PFM) WITH FREQUENCY = 4MHz

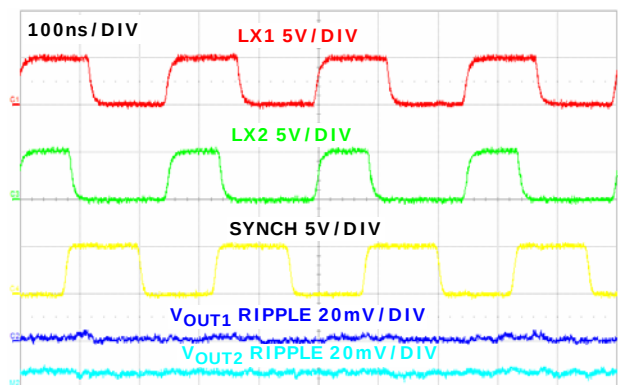


FIGURE 36. CH1 AND CH2 STEADY STATE OPERATION AT NO LOAD (PFM) WITH FREQUENCY = 4MHz

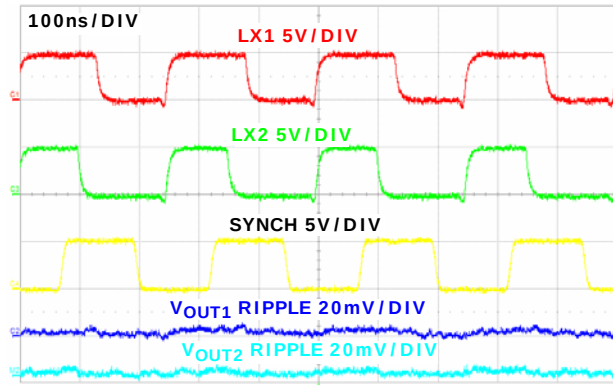


FIGURE 37. CH1 AND CH2 STEADY STATE OPERATION AT FULL LOAD (PFM) WITH FREQUENCY = 4MHz

Typical Operating Performance

Unless otherwise noted, operating conditions are: $T_A = +25^\circ\text{C}$, $V_{IN} = 2.75\text{V to } 5.5\text{V}$, $EN = V_{IN}$, $L_1 = L_2 = 2.2\mu\text{H}$, $C_1 = 10\mu\text{F}$, $C_2 = C_4 = 10\mu\text{F}$, $V_{OUT1} = 2.5\text{V}$, $V_{OUT2} = 1.8\text{V}$, $I_{OUT1} = I_{OUT2} = 0\text{A to } 800\text{mA}$. (Continued)

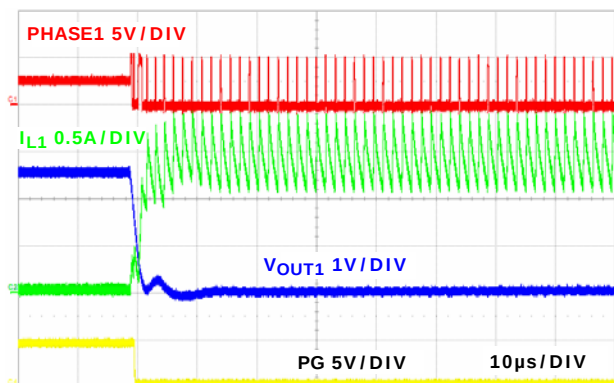


FIGURE 38. OUTPUT SHORT CIRCUIT CHANNEL 1

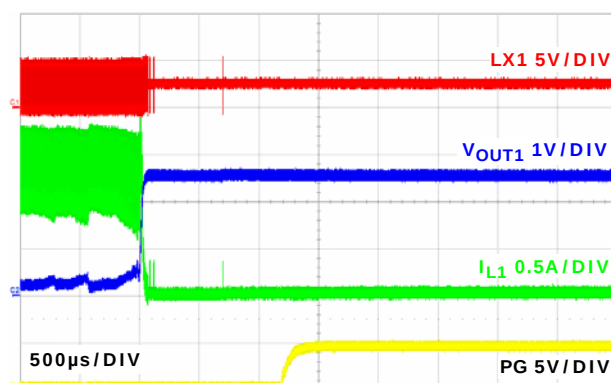


FIGURE 39. OUTPUT SHORT CIRCUIT RECOVERY CHANNEL 1

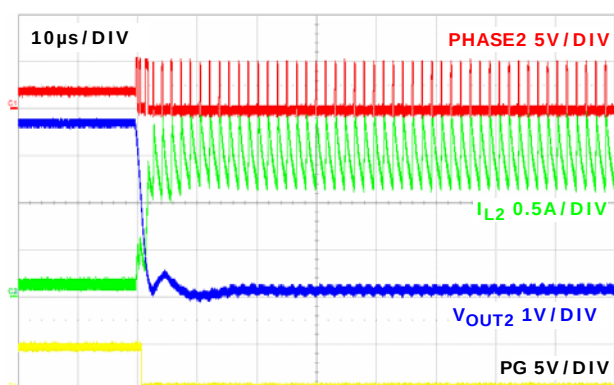


FIGURE 40. OUTPUT SHORT CIRCUIT CHANNEL 2

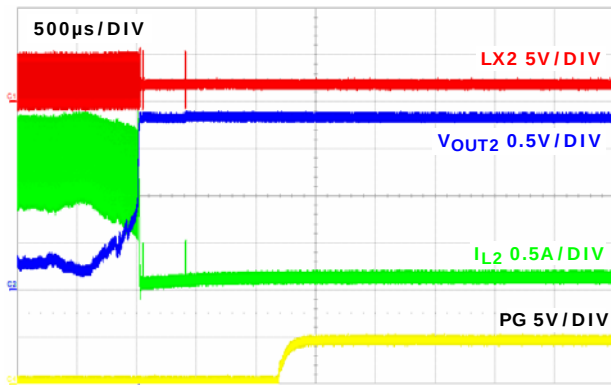


FIGURE 41. OUTPUT SHORT CIRCUIT RECOVERY CHANNEL 2

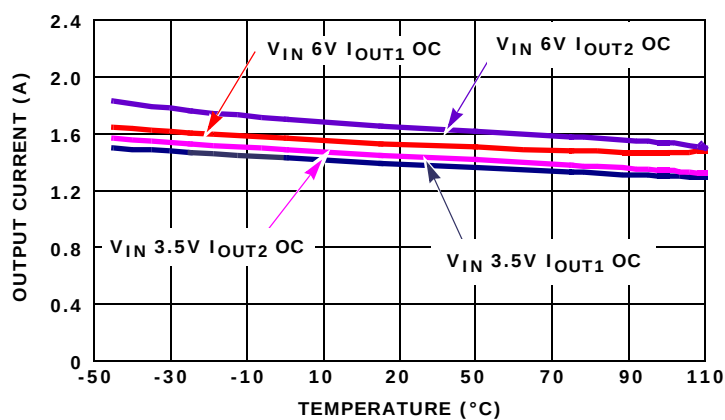
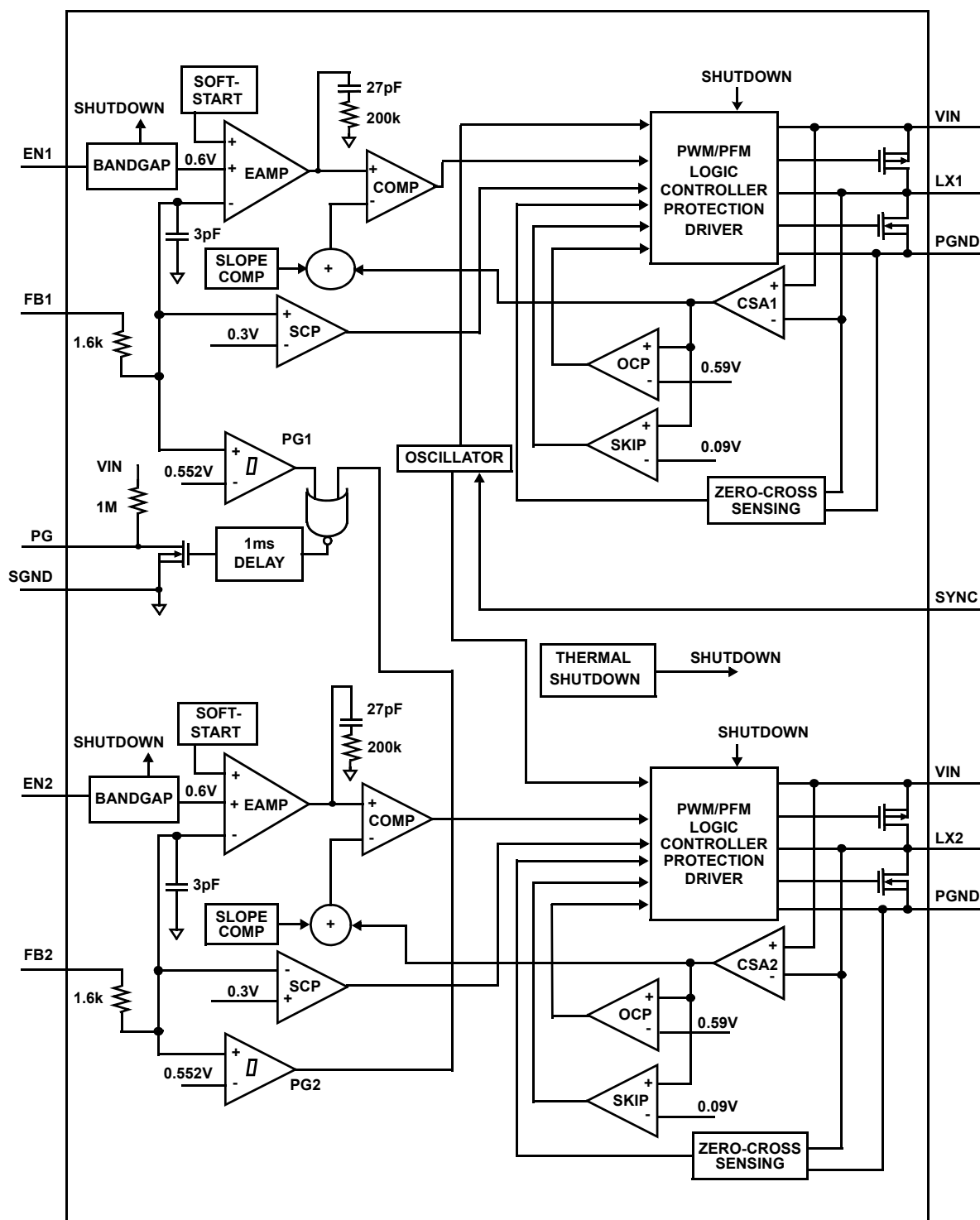


FIGURE 42. OUTPUT CURRENT LIMIT vs TEMPERATURE

Block Diagram



Theory of Operation

The ISL8088 is a dual 800mA step-down switching regulator optimized for battery-powered or mobile applications. The regulator operates at 2.25MHz fixed switching frequency under heavy load conditions to allow small external inductor and capacitors to be used for minimal printed-circuit board (PCB) area. At light load, the regulator reduces the switching frequency, unless forced to the fixed frequency, to minimize the switching loss and to maximize the battery life. The two channels are in-phase operation. The quiescent current when the outputs are not loaded is typically only 30 μ A. The supply current is typically only 6.5 μ A when the regulator is shut down.

PWM Control Scheme

Pulling the SYNC pin LOW (<0.4V) forces the converter into PWM mode in the next switching cycle regardless of output current. Each of the channels of the ISL8088 employ the current-mode pulse-width modulation (PWM) control scheme for fast transient response and pulse-by-pulse current limiting shown in the “Block Diagram” on page 13. The current loop consists of the oscillator, the PWM comparator COMP, current sensing circuit, and the slope compensation for the current loop stability. The current sensing circuit consists of the resistance of the P-Channel MOSFET when it is turned on and the current sense amplifier CSA1 (or CSA2 on Channel 2). The gain for the current sensing circuit is typically 0.285V/A. The control reference for the current loops comes from the error amplifier EAMP of the voltage loop.

The PWM operation is initialized by the clock from the oscillator. The P-Channel MOSFET is turned on at the beginning of a PWM cycle and the current in the MOSFET starts to ramp-up. When the sum of the current amplifier CSA1 (or CSA2) and the compensation slope (0.33V/ μ s) reaches the control reference of the current loop, the PWM comparator COMP sends a signal to the PWM logic to turn off the P-MOSFET and to turn on the N-Channel MOSFET. The N-MOSFET stays on until the end of the PWM cycle. Figure 43 shows the typical operating waveforms during the PWM operation. The dotted lines illustrate the sum of the compensation ramp and the current-sense amplifier CSA-output.

The output voltage is regulated by controlling the reference voltage to the current loop. The bandgap circuit outputs a 0.6V reference voltage to the voltage control loop. The feedback signal

comes from the V_{FB} pin. The soft-start block only affects the operation during the start-up and will be discussed separately shortly. The error amplifier is a transconductance amplifier that converts the voltage error signal to a current output. The voltage loop is internally compensated with the 27pF and 200k Ω RC network. The maximum EAMP voltage output is precisely clamped to 0.8V.

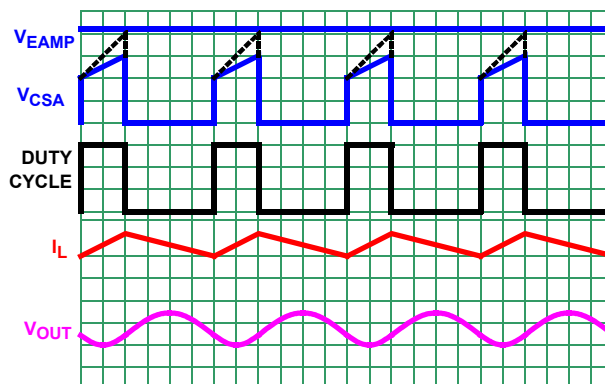


FIGURE 43. PWM OPERATION WAVEFORMS

SKIP Mode

Pulling the SYNC pin HIGH (>2.0V) forces the converter into PFM mode. The ISL8088 enters a pulse-skipping mode at light load to minimize the switching loss by reducing the switching frequency. Figure 44 illustrates the skip-mode operation. A zero-cross sensing circuit shown in the “Block Diagram” on page 13 monitors the N-MOSFET current for zero crossing. When 8 consecutive cycles of the N-MOSFET crossing zero are detected, the regulator enters the skip mode. During the 8 detecting cycles, the current in the inductor is allowed to become negative. The counter is reset to zero when the current in any cycle does not cross zero.

Once the skip mode is entered, the pulse modulation starts being controlled by the SKIP comparator shown in the “Block Diagram” on page 13. Each pulse cycle is still synchronized by the PWM clock. The P-MOSFET is turned on at the clock and turned off when its current reaches the threshold of 250mA. As the average inductor current in each cycle is higher than the average current of the load, the output voltage rises cycle over cycle. When the output voltage reaches 1.5% above the nominal voltage, the

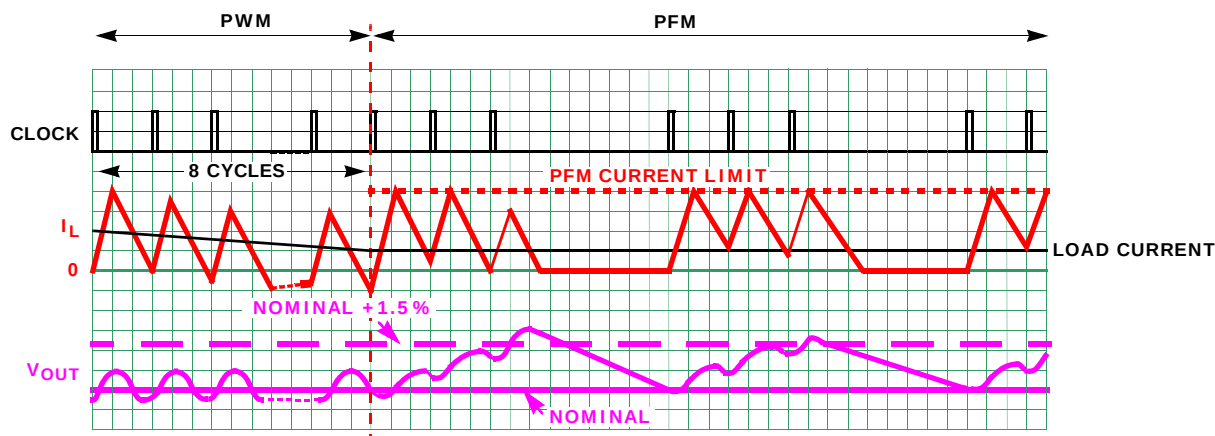


FIGURE 44. SKIP MODE OPERATION WAVEFORMS

P-MOSFET is turned off immediately. Then the inductor current is fully discharged to zero and stays at zero. The output voltage reduces gradually due to the load current discharging the output capacitor. When the output voltage drops to the nominal voltage, the P-MOSFET will be turned on again at the clock, repeating the previous operations.

The regulator resumes normal PWM mode operation when the output voltage drops 1.5% below the nominal voltage.

Synchronization Control

The frequency of operation can be synchronized up to 4MHz by an external signal applied to the SYNC pin. The falling edge on the SYNC triggered the rising edge of the PWM ON pulse.

Overcurrent Protection

CSA1 and CSA2 is used to monitor output 1 and output 2 channels respectively. The overcurrent protection is realized by monitoring the CSA_ output with the OCP threshold logic, as shown in "Block Diagram" on page 13. The current sensing circuit has a gain of 0.285V/A, from the P-MOSFET current to the CSA_ output. When the CSA_ output reaches the threshold of 590mV, the OCP comparator is tripped to turn off the P-MOSFET immediately. The overcurrent function protects the switching converter from a shorted output by monitoring the current flowing through the upper MOSFETs.

Upon detection of overcurrent condition, the upper MOSFET will be immediately turned off and will not be turned on again until the next switching cycle.

PG

The power-good signal, (PG) monitors both of the output channels. When powering up, the open-collector power-on-reset output holds low for about 1ms after V_{O1} and V_{O2} reaches the preset voltages. The PG output also serves as a 1ms delayed Power-Good signal. If one of the output is disabled, then PG only monitors the active channels. There is an internal 1M Ω pull-up resistor.

TABLE 1. PG

EN1	EN2	PG1 INTERNAL	PG2 INTERNAL	PG
0	0	X	X	0
0	1	X	1	1
1	0	1	X	1
1	1	1	1	1

UVLO

When the input voltage is below the undervoltage lock out (UVLO) threshold, the regulator is disabled.

Enable

The enable (EN1, EN2) input allows user to control the turning on or off the regulator for purposes such as power-up sequencing. The regulator is enabled, there is typically a 600 μ s delay for waking up the bandgap reference, then the soft start-up begins.

Soft-Start-Up

The soft-start-up eliminates the in-rush current during the start-up. The soft-start block outputs a ramp reference to both the voltage loop and the current loop. The two ramps limit the inductor current rising speed as well as the output voltage speed so that the output voltage rises in a controlled fashion. At the very beginning of the start-up, the feedback voltage is less than 0.2V; hence the PWM operating frequency is 1/3 of the normal frequency.

In force PWM mode, the IC will continue to start-up in PFM mode to support pre-biased load applications.

Discharge Mode (Soft-Stop)

When a transition to shutdown mode occurs, or the output undervoltage fault latch is set, the outputs discharge to GND through an internal 100 Ω switch.

Power MOSFETs

The power MOSFETs are optimize for best efficiency. The ON-resistance for the P-MOSFET is typically 180m Ω and the ON-resistance for the N-MOSFET is typical 180m Ω .

100% Duty Cycle

The ISL8088 features 100% duty cycle operation to maximize the battery life. When the battery voltage drops to a level that the ISL8088 can no longer maintain the regulation at the output, the regulator completely turns on the P-MOSFET. The maximum dropout voltage under the 100% duty-cycle operation is the product of the load current and the ON-resistance of the P-MOSFET.

Thermal Shut-Down

The ISL8088 has built-in thermal protection. When the internal temperature reaches +150 $^{\circ}$ C, the regulator is completely shut down. As the temperature drops to +130 $^{\circ}$ C, the ISL8088 resumes operation by stepping through a soft-start-up.

Applications Information

Output Inductor and Capacitor Selection

To consider steady state and transient operation, ISL8088 typically uses a 2.2 μ H output inductor. Higher or lower inductor values can be used to optimize the total converter system performance. For example, for higher output voltage 3.3V applications, in order to decrease the inductor current ripple and output voltage ripple, the output inductor value can be increased. The inductor ripple current can be expressed as shown in Equation 1:

$$\Delta I = \frac{V_O \cdot \left(1 - \frac{V_O}{V_{IN}}\right)}{L \cdot f_S} \quad (\text{EQ. 1})$$

The inductor's saturation current rating needs be at least larger than the peak current. The ISL8088 protects the typical peak current 1.2A. The saturation current needs be over 1.8A for maximum output current application.

ISL8088 uses internal compensation network and the output capacitor value is dependent on the output voltage. The ceramic capacitor is recommended to be X5R or X7R. The recommended minimum output capacitor values are shown in Table 2 for the ISL8088.

TABLE 2. OUTPUT CAPACITOR VALUE vs V_{OUT} ISL8088

V_{OUT} (V)	C_{OUT} (μ F)	L (μ H)
0.8	10	1.0~2.2
1.2	10	1.0~2.2
1.6	10	1.0~2.2
1.8	10	1.5~3.3
2.5	10	1.5~3.3
3.3	6.8	1.5~4.7
3.6	8.6	1.5~4.7

In Table 2, the minimum output capacitor value is given for different output voltage to make sure the whole converter system is stable.

Output Voltage Selection

The output voltage of the regulator can be programmed via an external resistor divider that is used to scale the output voltage relative to the internal reference voltage and feed it back to the inverting input of the error amplifier. Refer to "Typical Application" on page 2.

The output voltage programming resistor, R_2 (or R_5 in Channel 2), will depend on the desired output voltage of the regulator. The value for the feedback resistor is typically between 0 Ω and 750k Ω as shown in Equation 2.

Let $R_3 = 100\text{k}\Omega$, then R_2 will be:

$$R_2 = R_3 \left(\frac{V_{OUT}}{V_{FB}} - 1 \right) \quad (\text{EQ. 2})$$

If the output voltage desired is 0.6V, then R_3 is left unpopulated and short R_2 . For faster response performance, add 47pF in parallel to R_2 .

Input Capacitor Selection

The main functions for the input capacitor is to provide decoupling of the parasitic inductance and to provide filtering function to prevent the switching current flowing back to the battery rail. One 10 μ F X5R or X7R ceramic capacitor is a good starting point for the input capacitor selection for both channels.

PCB Layout Recommendation

The PCB layout is a very important converter design step to make sure the designed converter works well. For ISL8088, the power loop is composed of the output inductor (L 's), the output capacitor (C_{OUT1} and C_{OUT2}), the LX's pins, and the GND pin. It is necessary to make the power loop as small as possible and the connecting traces among them should be direct, short and wide. The switching node of the converter, the LX_ pins, and the traces connected to the node are very noisy, so keep the voltage feedback trace away from these noisy traces. The input capacitor should be placed as closely as possible to the VIN pin. The ground of input and output capacitors should be connected as closely as possible. The heat of the IC is mainly dissipated through the thermal pad. Maximizing the copper area connected to the thermal pad is preferable. In addition, a solid ground plane is helpful for better EMI performance. It is recommended to add at least 5 vias ground connection within the pad for the best thermal relief.

Revision History

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please go to web to make sure you have the latest Rev.

DATE	REVISION	CHANGE
5/6/11	FN6858.2	Converted to new template Updated Intersil Trademark statement at bottom of page 1 per directive from Legal. Removed ISL8088IRZ-T from Ordering Info table, and updated Tape & Reel note in Ordering Information from "Please refer to TB347 for details on reel specifications." to new standard "Add "-T*" suffix for tape and reel. Please refer to TB347 for details on reel specifications." The "*" covers all possible tape and reel options. Changed the time scale on Figs. 24, 25, 26, 27, 28 and 29 from 50μs/DIV to 500μs/DIV "Soft-Start-Up" on page 15, last sentence, changed output voltage to feedback voltage
3/18/10	FN6858.1	Page 13: Added inverter symbol in Block Diagram to PG OR Gate. Per new datasheet standard, moved: Pin Configuration from pg1 and Pin Desc table from pg 2, both to pg 3. Typ App diagram from pg 3 to pg 2
9/21/09	FN6858.0	Initial release

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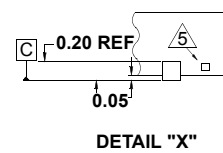
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Rev 2, 09/09



1. Dimensions are in millimeters.
Dimensions in () for Reference Only.
2. Dimensioning and tolerancing conform to AMSE Y14.5m-1994.
3. Unless otherwise specified, tolerance : Decimal ± 0.05
4. Dimension b applies to the metallized terminal and is measured between 0.18mm and 0.30mm from the terminal tip.
5. Tiebar shown (if present) is a non-functional feature.
6. The configuration of the pin #1 identifier is optional, but must be located within the zone indicated. The pin #1 identifier may be either a mold or mark feature.
7. COMPLIANT TO JEDEC MO-229-WEED-3 except for E-PAD dimensions.