# **HEF4021B**

# 8-bit static shift register

Rev. 11 — 1 December 2021

Product data sheet

## 1. General description

The HEF4021B is an 8-bit static shift register (parallel-to-serial converter) with a synchronous serial data input (DS), a clock input (CP), an asynchronous active HIGH parallel load input (PL), eight asynchronous parallel data inputs (D0 to D7) and buffered parallel outputs from the last three stages (Q5 to Q7). Each register stage is a D-type master-slave flip-flop with a set direct (SD) and clear direct (CD) input. Information on D0 to D7 is asynchronously loaded into the register while PL is HIGH, independent of CP and DS. When PL is LOW, data on DS is shifted into the first register position and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. Schmitt trigger action makes the clock input highly tolerant of slower rise and fall times

The device operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

### 2. Features and benefits

- Wide supply voltage range from 3.0 V to 15.0 V
- · CMOS low power dissipation
- High noise immunity
- Tolerant of slower rise and fall times
- · Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Complies with JEDEC standard JESD 13-B
- ESD protection:
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-B exceeds 200 V
- Specified from -40 °C to +85 °C and from -40 °C to +125 °C

## 3. Ordering information

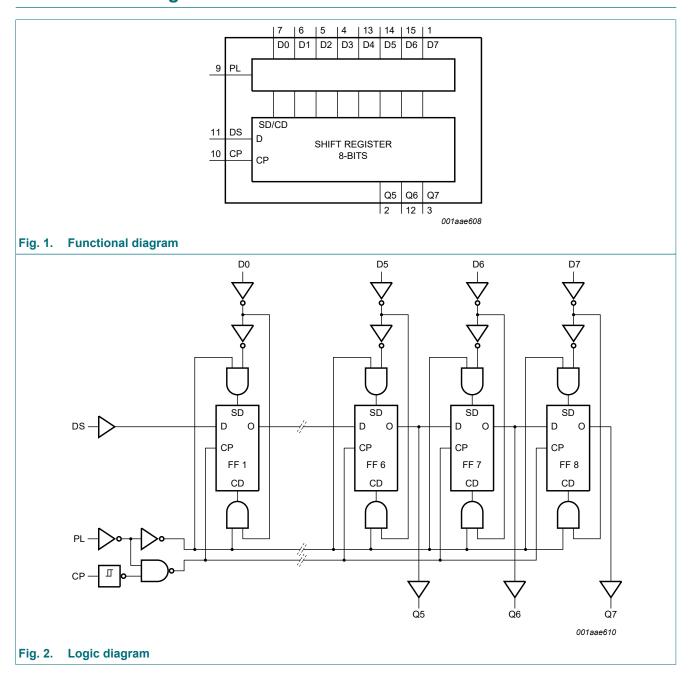
**Table 1. Ordering information** 

Type number	Package	Package										
	Temperature range	Name	Description	Version								
HEF4021BT	-40 °C to +125 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1								
HEF4021BTT	-40 °C to +125 °C	TSSOP16	plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1								



8-bit static shift register

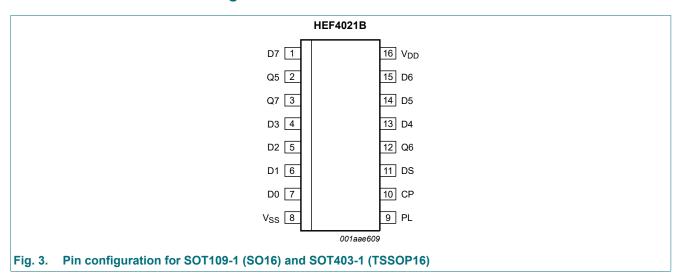
# 4. Functional diagram



8-bit static shift register

# 5. Pinning information

## 5.1. Pinning



# 5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
Q5, Q6, Q7	2, 12, 3	buffered parallel output from the last three stages
D0, D1, D2, D3, D4, D5, D6, D7	7, 6, 5, 4, 13, 14,15, 1	parallel data input
V <sub>SS</sub>	8	ground supply voltage
PL	9	parallel load input
CP	10	clock input (LOW-to-HIGH edge-triggered)
DS	11	serial data input
$V_{DD}$	16	supply voltage

8-bit static shift register

# 6. Functional description

#### Table 3. Function table

 $H = HIGH \ voltage \ level; \ L = LOW \ voltage \ level; \ X = don't \ care;$ 

 $\uparrow$  = LOW to HIGH clock transition;  $\downarrow$  = HIGH to LOW clock transition;

data n = data (HIGH or LOW) on the DS input at the  $n^{th} \uparrow CP$  transition.

Inputs			Outputs	Outputs						
СР	DS	PL	Q5	Q6	Q7					
	'	'	'		-					
1	data 1	L	Х	X	X					
1	data 2	L.	X	X	X					
1	data 3	L	Х	X	X					
1	X	L	data 1	X	X					
1	X	L	data 2	data 1	X					
1	X	L	data 3	data 2	data 1					
$\downarrow$	X	L	no change	no change	no change					
i		'	,		,					
Х	X	Н	D5	D6	D7					
	↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑ ↑	CP         DS           ↑         data 1           ↑         data 2           ↑         data 3           ↑         X           ↑         X           ↓         X           ↓         X	CP         DS         PL           ↑         data 1         L           ↑         data 2         L           ↑         X         L           ↑         X         L           ↑         X         L           ↓         X         L           ↓         X         L	CP         DS         PL         Q5           ↑         data 1         L         X           ↑         data 2         L         X           ↑         X         L         X           ↑         X         L         data 1           ↑         X         L         data 2           ↑         X         L         data 3           ↓         X         L         no change	CP         DS         PL         Q5         Q6           ↑         data 1         L         X         X           ↑         data 2         L         X         X           ↑         data 3         L         X         X           ↑         X         L         data 1         X           ↑         X         L         data 2         data 1           ↑         X         L         data 3         data 2           ↓         X         L         no change         no change					

# 7. Limiting values

### **Table 4. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{I} < -0.5 \text{ V or } V_{I} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
VI	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{O} < -0.5 \text{ V or } V_{O} > V_{DD} + 0.5 \text{ V}$	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+125	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> -40 °C to +125 °C [1]	-	500	mW
Р	power dissipation	per output	-	100	mW

<sup>[1]</sup> For SOT109-1 (SO16) package:  $P_{tot}$  derates linearly with 12.4 mW/K above 110 °C. For SOT403-1 (TSSOP16) package:  $P_{tot}$  derates linearly with 8.5 mW/K above 91 °C.

8-bit static shift register

# 8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{DD}$	supply voltage		3	-	15	V
VI	input voltage		0	-	$V_{DD}$	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+125	°C
Δt/ΔV	input transition rise and fall rate	V <sub>DD</sub> = 5 V	-	-	3.75	μs/V
		V <sub>DD</sub> = 10 V	-	-	0.5	μs/V
		V <sub>DD</sub> = 15 V	-	-	0.08	μs/V

## 9. Static characteristics

## **Table 6. Static characteristics**

 $V_{SS} = 0 \ V$ ;  $V_I = V_{SS} \ or \ V_{DD} \ unless \ otherwise \ specified.$ 

Symbol	Parameter	Conditions	$V_{DD}$	T <sub>amb</sub> =	-40 °C	T <sub>amb</sub> =	+25 °C	T <sub>amb</sub> =	+85 °C	T <sub>amb</sub> =	+125 °C	Unit	
				Min	Max	Min	Max	Min	Max	Min	Max		
V <sub>IH</sub>	HIGH-level	I <sub>O</sub>   < 1 μΑ	5 V	3.5	-	3.5	-	3.5	-	3.5	-	V	
	input voltage		10 V	7.0	-	7.0	-	7.0	-	7.0	-	V	
			15 V	11.0	-	11.0	-	11.0	-	11.0	-	V	
$V_{IL}$	LOW-level	I <sub>O</sub>   < 1 μΑ	5 V	-	1.5	-	1.5	-	1.5	-	1.5	V	
	input voltage		10 V	-	3.0	-	3.0	-	3.0	-	3.0	V	
			15 V	-	4.0	-	4.0	-	4.0	-	4.0	V	
V <sub>OH</sub>	output voltage	I <sub>O</sub>   < 1 µA	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V	
		· ·		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V	
$V_{OL}$	LOW-level output voltage	I <sub>O</sub>   < 1 μΑ	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V	
			10 V	-	0.05	-	0.05	-	0.05	-	0.05	V	
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V	
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA	
		V <sub>O</sub> = 4.6 V	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA	
		V <sub>O</sub> = 9.5 V	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA	
		V <sub>O</sub> = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA	
I <sub>OL</sub>	LOW-level	V <sub>O</sub> = 0.4 V	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA	
	output current	V <sub>O</sub> = 0.5 V	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA	
		V <sub>O</sub> = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA	
l <sub>l</sub>	input leakage current	V <sub>DD</sub> = 15 V	15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μA	
I <sub>DD</sub>	supply	I <sub>O</sub> = 0 A	5 V	-	5	-	5	-	150	-	150	μΑ	
	current		10 V	-	10	-	10	-	300	-	300	μΑ	
			15 V	-	20	-	20	-	600	-	600	μΑ	
Cı	input capacitance		-	-	-	-	7.5	-	-	-	-	pF	

8-bit static shift register

# 10. Dynamic characteristics

**Table 7. Dynamic characteristics** 

 $V_{SS}$  = 0 V;  $T_{amb}$  = 25 °C unless otherwise specified; for test circuit see Fig. 7.

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula[1]	Min	Тур	Max	Unit
t <sub>PHL</sub>	HIGH to LOW	CP to Qn; see Fig. 4	5 V	98 ns + (0.55 ns/pF)C <sub>L</sub>	-	125	250	ns
	propagation delay		10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		PL to Qn; see Fig. 4	5 V	93 ns + (0.55 ns/pF)C <sub>L</sub>	-	120	240	ns
			10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
t <sub>PLH</sub>	LOW to HIGH	CP to Qn; see Fig. 4	5 V	88 ns + (0.55 ns/pF)C <sub>L</sub>	-	115	230	ns
	propagation delay		10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		PL to Qnl; see Fig. 4	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns
			10 V	39 ns + (0.23 ns/pF)C <sub>L</sub>	-	50	100	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
t <sub>t</sub>	transition time	Qn; see Fig. 4	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
t <sub>su</sub>			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
	set-up time	DS to CP; see Fig. 5	5 V		+25	-15	-	ns
			10 V		+25	-10	-	ns
			15 V		+15	-5	-	ns
		Dn to PL; see Fig. 6	5 V		50	25	-	ns
			10 V		30	10	-	ns
			15 V		20	5	-	ns
t <sub>h</sub>	hold time	DS to CP; see Fig. 5	5 V		40	20	-	ns
			10 V		20	10	-	ns
			15 V		15	8	-	ns
		Dn to PL; see Fig. 6	5 V		+15	-10	-	ns
			10 V		15	0	-	ns
			15 V		15	0	-	ns
t <sub>W</sub>	pulse width	CP = LOW;	5 V		70	35	-	ns
		minimum width;	10 V		30	15	-	ns
		see <u>Fig. 5</u>	15 V		24	12	-	ns
		PL = HIGH;	5 V		70	35	-	ns
		minimum width;	10 V		30	15	-	ns
		see <u>Fig. 6</u>	15 V		24	12	-	ns
t <sub>rec</sub>	recovery time	PL input; see Fig. 6	5 V		50	10	-	ns
			10 V		40	5	-	ns
			15 V		35	5	-	ns

### 8-bit static shift register

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula[1]	Min	Тур	Max	Unit
f <sub>clk(max)</sub>		CP input; see Fig. 5	5 V		6	13	-	MHz
	frequency		10 V		15	30	-	MHz
			15 V		20	40	-	MHz

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown ( $C_L$  in pF).

### Table 8. Dynamic power dissipation P<sub>D</sub>

 $P_D$  can be calculated from the formulas shown.  $V_{SS}$  = 0 V;  $t_r$  =  $t_f$  ≤ 20 ns;  $T_{amb}$  = 25 °C.

Symbol	Parameter	$V_{DD}$	Typical formula for P <sub>D</sub> (μW)	where:
$P_D$	dynamic power	5 V	. (0 2, 22	f <sub>i</sub> = input frequency in MHz
	dissipation		P	f <sub>o</sub> = output frequency in MHz C <sub>L</sub> = output load capacitance in pF
		15 V	$P_D = 12000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$	$V_{DD}$ = supply voltage in V $\Sigma(f_o \times C_L)$ = sum of the outputs

## 10.1. Waveforms and test circuit

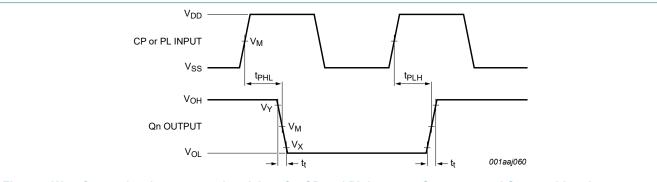


Fig. 4. Waveforms showing propagation delays for CP and PL inputs to Qn output and Qn transition times

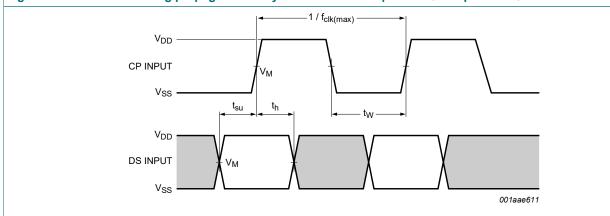
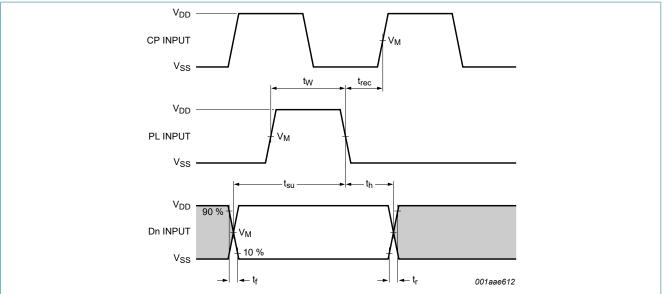


Fig. 5. Waveforms showing minimum clock pulse width, set-up time, and hold time for CP and DS

### 8-bit static shift register

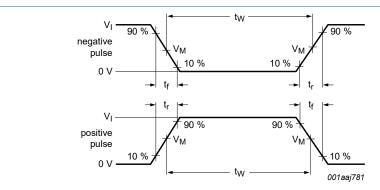


Set-up times and hold times are shown as positive values but may be specified as negative values. Measurement points are given in <u>Table 9</u>.

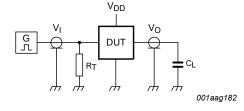
Fig. 6. Waveforms showing minimum pulse width and recovery time for PL; set-up and hold times for Dn to PL

**Table 9. Measurement points** 

Supply voltage	Input	Output							
V <sub>DD</sub> V <sub>M</sub>		V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>					
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>	0.1V <sub>DD</sub>	0.9V <sub>DD</sub>					



### a. Input waveform



### b. Test circuit

Test data is given in Table 10.

Definitions for test circuit:

C<sub>L</sub> = load capacitance including jig and probe capacitance.

 $R_T$  = termination resistance should be equal to the output impedance  $Z_0$  of the pulse generator.

Fig. 7. Test circuit for measuring switching times

## 8-bit static shift register

## Table 10. Test data

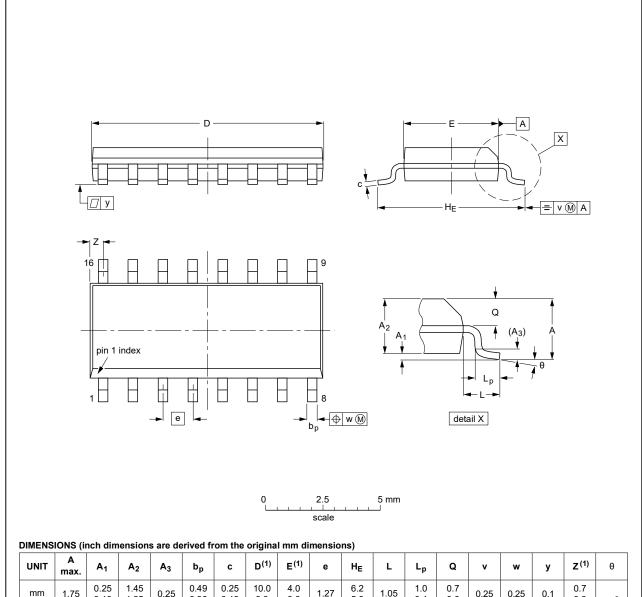
Supply voltage	Input	Load	
$V_{DD}$	V <sub>I</sub>	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	V <sub>SS</sub> or V <sub>DD</sub>	≤ 20 ns	50 pF

8-bit static shift register

# 11. Package outline

### SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



	UNIT	A max.	<b>A</b> <sub>1</sub>	A <sub>2</sub>	<b>A</b> <sub>3</sub>	bp	С	D <sup>(1)</sup>	E <sup>(1)</sup>	е	HE	L	Lp	q	v	w	у	Z <sup>(1)</sup>	θ
	mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	10.0 9.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8°
i	nches	0.069	0.010 0.004	0.057 0.049	0.01		0.0100 0.0075	0.39 0.38	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.020	0.01	0.01	0.004	0.028 0.012	0°

#### Note

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

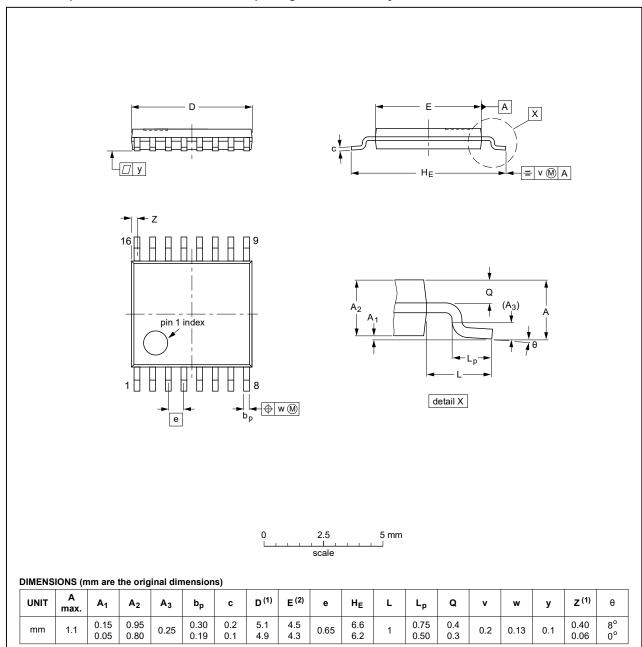
OUTLINE	REFERENCES				EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
SOT109-1	076E07	MS-012				<del>99-12-27</del> 03-02-19

Fig. 8. Package outline SOT109-1 (SO16)

## 8-bit static shift register

TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

SOT403-1



#### Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE	REFERENCES				EUROPEAN	ISSUE DATE
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE
SOT403-1		MO-153			$ \  \   \bigoplus  \big($	<del>99-12-27</del> 03-02-18

Fig. 9. Package outline SOT403-1 (TSSOP16)

8-bit static shift register

## 12. Abbreviations

### **Table 11. Abbreviations**

Acronym	Description
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MM	Machine Model

# 13. Revision history

### **Table 12. Revision history**

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4021B v.11	20211201	Product data sheet	-	HEF4021B v.10
Modifications:	Nexperia.  • Legal texts ha • Section 2 upd	this data sheet has been redes we been adapted to the new co ated. iing values for P <sub>tot</sub> total power o	ompany name where	, ,
HEF4021B v.10	20160321	Product data sheet	-	HEF4021B v.9
Modifications:	Type number	HEF4021BP (SOT38-4) remov	ed.	
HEF4021B v.9	20130830	Product data sheet	-	HEF4021B v.8
Modifications:	Added type nu	umber HEF4021BTT.		
HEF4021B v.8	20111118	Product data sheet	-	HEF4021B v.7
Modifications:	_	updated. ection 1 and Section 2. cations" removed.		
HEF4021B v.7	20111010	Product data sheet	-	HEF4021B v.6
HEF4021B v.6	20091127	Product data sheet	-	HEF4021B v.5
HEF4021B v.5	20090707	Product data sheet	-	HEF4021B v.4
HEF4021B v.4	20081110	Product data sheet	-	HEF4021B_CNV v.3
HEF4021B_CNV v.3	19950101	Product specification	-	HEF4021B_CNV v.2
HEF4021B_CNV v.2	19950101	Product specification	-	-

### 8-bit static shift register

## 14. Legal information

#### **Data sheet status**

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
- The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <a href="https://www.nexperia.com">https://www.nexperia.com</a>.

#### **Definitions**

**Draft** — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. Nexperia does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local Nexperia sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

Product specification — The information and data provided in a Product data sheet shall define the specification of the product as agreed between Nexperia and its customer, unless Nexperia and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the Nexperia product is deemed to offer functions and qualities beyond those described in the Product data sheet.

#### **Disclaimers**

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, Nexperia does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. Nexperia takes no responsibility for the content in this document if provided by an information source outside of Nexperia.

In no event shall Nexperia be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, Nexperia's aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of Nexperia.

Right to make changes — Nexperia reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — Nexperia products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an Nexperia product can reasonably be expected to result in personal

injury, death or severe property or environmental damage. Nexperia and its suppliers accept no liability for inclusion and/or use of Nexperia products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Quick reference data** — The Quick reference data is an extract of the product data given in the Limiting values and Characteristics sections of this document, and as such is not complete, exhaustive or legally binding.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. Nexperia makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using Nexperia products, and Nexperia accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the Nexperia product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

Nexperia does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using Nexperia products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). Nexperia does not accept any liability in this respect.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

Terms and conditions of commercial sale — Nexperia products are sold subject to the general terms and conditions of commercial sale, as published at <a href="http://www.nexperia.com/profile/terms">http://www.nexperia.com/profile/terms</a>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. Nexperia hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of Nexperia products by sustained.

No offer to sell or license — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

Non-automotive qualified products — Unless this data sheet expressly states that this specific Nexperia product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. Nexperia accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without Nexperia's warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond Nexperia's specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies Nexperia for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond Nexperia's standard warranty and Nexperia's product specifications.

**Translations** — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

#### **Trademarks**

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

HEF4021B

All information provided in this document is subject to legal disclaimers.

© Nexperia B.V. 2021. All rights reserved

## 8-bit static shift register

## **Contents**

1.	General description	1
2.	Features and benefits	1
3.	Ordering information	1
4.	Functional diagram	.2
5.	Pinning information	3
5.1	. Pinning	3
5.2	. Pin description	3
6.	Functional description	4
7.	Limiting values	4
8.	Recommended operating conditions	5
9.	Static characteristics	.5
10.	Dynamic characteristics	6
10.	Waveforms and test circuit	7
11.	Package outline1	0
12.	Abbreviations1	2
13.	Revision history1	2
14.	Legal information1	3

For more information, please visit: http://www.nexperia.com For sales office addresses, please send an email to: salesaddresses@nexperia.com Date of release: 1 December 2021

<sup>©</sup> Nexperia B.V. 2021. All rights reserved