# **RoHS Recast Compliant**

# M.2 2280 Flash Drive

**P201-M Product Specifications** 

**December 23, 2014** 

Version 1.1



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### **Features:**

#### Standard SATA Interface Compliance

- Serial ATA Revision 3.2 compliance
- SATA 6.0 Gbps interface
- ATA-8 command set

#### Capacities

- 16, 32, 64, 128, 256 GB

#### Performance\*

Burst read/write: 600 MB/secSustained read: up to 515 MB/secSustained write: up to 180 MB/sec

#### Flash Management

- Built-in hardware ECC, enabling up to 72 bit correction per 1K bytes
- Static/dynamic wear-leveling
- Flash bad-block management
- S.M.A.R.T.
- Power Failure Management
- ATA Secure Erase
- TRIM

#### • NAND Flash Type: MLC

#### • Temperature ranges

Operating: 0°C to 70°CStorage: -40°C to 85°C

#### Supply voltage

 $-3.3 V \pm 5\%$ 

#### Power consumption (typical)\*

Active mode: 600 mAIdle mode: 90 mA

#### Connector type

- 75-pin SATA-based M.2 module pinout

#### Form factor

- M.2 2280 form factor
- Dimensions: 80.00x22.00x3.80, unit: mm

#### Shock & Vibration\*\*\*

Shock:1500 GVibration: 15 G

MTBF: >2,000,000 hours

#### SATA Power Management

- RoHS Recast compliant (complies with 2011/65/EU standard)
- Device Sleep mode (optional)

<sup>\*</sup>Varies from capacities. The values for performances and power consumptions presented are typical and may vary depending on flash configurations or platform settings. The term idle refers to the standby state of the device.

\*\*Non-operating



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## 1. General Description

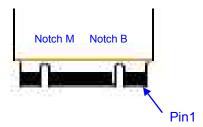
Apacer's P201-M is the next generation modularized Solid State Drive (SSD) with the shape of all new M.2 form factor, aimed to be the more suitable for mobile and compact computers with standard width at only 22.00 mm. P201-M appears in M.2 2280 mechanical dimensions and is believed to be the leading add-in storage solution for future host computing systems.

The M.2 SSD is designed with SATA-based connector pinouts, providing full compliance with the latest SATA Revision 3.2 interface specifications. Aside from SATA compliance, P201-M delivers exceptional performance and power efficiency. On the other hand, the extreme thin and light form factor makes P201-M the ideal choice for mobile computing systems, which appears to be the trend in near future.

Regarding reliability, P201-M is built with a powerful SATA controller that supports on-the-module ECC as well as efficient wear leveling scheme. In terms of power efficiency, P201-M is compliant with SATA 6.0 Gbps interface standard so that it can operate on SATA power management modes, which greatly save on power consumption.

## 2. Pin Assignments

This connector does not support hot plug capability. There are a total of 75 pins. 12 pin locations are used for mechanical key locations; this allows such a module to plug into both Key B and Key M connectors.



Pin	Туре	Description
1	CONFIG_3	Ground (according to M.2 configurations for SSD-SATA definition)
2	3.3V	Supply Pin, 3.3V
3	GND	Ground
4	3.3V	Supply pin, 3.3V
5	No connect	No connect
6	Not available	No connect (used for other purposes)
7	Not available	No connect (used for other purposes)
8	Not available	No connect (used for other purposes)
9	No connect	No connect
10	DAS/DSS	Device Activity Signal/Disable Staggered Spin-up
11	No connect	No connect (used for other purposes)
12	(removed for key)	Mechanical notch B



13	(removed for key)	Mechanical notch B
14	(removed for key)	Mechanical notch B
15	(removed for key)	Mechanical notch B
16	(removed for key)	Mechanical notch B
17	(removed for key)	Mechanical notch B
18	(removed for key)	Mechanical notch B
19	(removed for key)	Mechanical notch B
20	Not available	No connect (used for other purposes)
21	CONFIG_0	Ground (according to M.2 configurations for SSD-SATA definition)
22	Not available	No connect (used for other purposes)
23	Not available	No connect (used for other purposes)
24	Not available	No connect (used for other purposes)
25	Not available	No connect (used for other purposes)
26	Not available	No connect (used for other purposes)
27	GND	Ground
28	Not available	No connect (used for other purposes)
29	PERn1	Not used
30	Not available	No connect (used for other purposes)
31	PERp1	Not used
32	Not available	No connect (used for other purposes)
33	GND	Ground
34	Not available	No connect (used for other purposes)
35	PETn1	Not used
36	Not available	No connect (used for other purposes)
37	PETp1	Not used
38	DEVSLP	Device Sleep, input. If driven high the host is informing the SSD to enter a low power state (optional)
39	GND	Ground
40	Not available	No connect (used for other purposes)
41	SATA-Rx+	Host receiver differential signal pair
42	Not available	No connect (used for other purposes)
43	SATA-Rx-	Host receiver differential signal pair
44	Not available	No connect (used for other purposes)
45	GND	Ground
46	Not available	No connect (used for other purposes)
47	SATA-Tx-	Host transmitter differential pair
48	Not available	No connect (used for other purposes)



49	SATA-Tx+	Host transmitter differential pair
50	PERST#	Not used
51	GND	Ground
52	CLKREQ#	Not used
53	REFCLKN	Not used
54	PEWAKE#	Not used
55	REFCLKP	Not used
56	MFG1	Manufacturing pin. Use determined by vendor (no connect on a host)
57	GND	Ground
58	MFG2	Manufacturing pin. Use determined by vendor (no connect on a host)
59	(removed for key)	Mechanical notch B
60	(removed for key)	Mechanical notch B
61	(removed for key)	Mechanical notch B
62	(removed for key)	Mechanical notch B
63	(removed for key)	Mechanical notch B
64	(removed for key)	Mechanical notch B
65	(removed for key)	Mechanical notch B
66	(removed for key)	Mechanical notch B
67	Not available	No connect (used for other purposes)
68	SUSCLK	Not used
69	CONFIG_1	Ground
70	3.3V	Supply pin, 3.3V
71	GND	Ground
72	3.3V	Supply pin, 3.3V
73	GND	Ground
74	3.3V	Supply pin, 3.3V
75	CONFIG_2	Ground



# 3. Product Specifications

## 3.1 Capacity

Capacity specification of P201-M is available as shown in Table 3-1. It lists the specific capacity and the default numbers of heads, sectors and cylinders for each product line.

Table 3-1: Capacity specifications

Capacity	Total bytes*	Cylinders	Heads	Sectors	Max LBA
16 GB	16,013,942,784	16,383	16	63	31,277,232
32 GB	32,017,047,552	16,383	16	63	62,533,296
64 GB	64,023,257,088	16,383	16	63	125,045,424
128 GB	128,035,676,160	16,383	16	63	250,069,680
256 GB	256,060,514,304	16,383	16	63	500,118,192

<sup>\*</sup>Display of total bytes varies from file systems, which means not all of the bytes can be used for storage.

LBA count addressed in the table above indicates total user storage capacity and will remain the same throughout the lifespan of the device. However, the total usable capacity of the SSD is most likely to be less than the total physical capacity because a small portion of the capacity is reserved for device maintenance usages.

#### 3.2 Performance

Performances of P201-M are listed below in table 3-2.

Table 3-2: Performance

Capacity Performance	16 GB	32 GB	64 GB	128 GB	256 GB
Sustained read (MB/s)	300	510	515	515	515
Sustained write (MB/s)	170	180	180	180	180

Note: Results were measured by CrystalDiskMark and may differ from various flash configurations or host system setting

<sup>\*\*</sup>Notes: 1 GB = 1,000,000,000 bytes; 1 sector = 512 bytes.



## 3.3 Environmental Specifications

Environmental specification of P201-M series follows MIL-STD-810 standards as shown in Table 3-3.

Table 3-3 P201-M environmental specifications

Item	Specification
Operating temperature	0~70°C
Non-operating temperature	-40~85°C
Operating humidity	40°C, 90%RH
Non-operating humidity	40°C, 93%RH
Vibration (Non-operating)	Frequency/Displacement: 20Hz~80Hz/1.52mm Frequency/Acceleration: 80Hz~2000Hz/20G X, Y, Z axis/60mins
shock (Non-operating)	1500G, 0.5ms
Drop (Non-operating)	80cm free fall, 6 face of each unit
Bending (non-operating)	≥20N, hold 1min/5times
Torque (non-operating)	0.5N-m or ±2.5 deg, hold 1min/5times
ESD (Electrostatic)	Passed (at relative temp/humidity: 24°C, 49%RH)

## 3.4 Mean Time Between Failures (MTBF)

Mean Time Between Failures (MTBF) is predicted based on reliability data for the individual components in P201-M. The prediction result for P201-M is more than 2,000,000 hours.

Notes about the MTBF:

The MTBF is predicated and calculated based on "Telcordia Technologies Special Report, SR-332, Issue 2" method.

## 3.5 Certification and Compliance

P201-M complies with the following standards:

- CE: EN55022 FCC:CISPR22
- BSMI 13438
- RoHS Recast



## 4. Flash Management

#### 4.1 Error Correction/Detection

P201-M implements a hardware ECC scheme, based on the BCH algorithm. It can detect and correct up to 72 bits error in 1K bytes.

#### 4.2 Bad Block Management

Current production technology is unable to guarantee total reliability of NAND flash memory array. When a flash memory device leaves factory, it comes with a minimal number of initial bad blocks during production or out-of-factory as there is no currently known technology that produce flash chips free of bad blocks. In addition, bad blocks may develop during program/erase cycles. When host performs program/erase command on a block, bad block may appear in Status Register. Since bad blocks are inevitable, the solution is to keep them in control. Apacer flash devices are programmed with ECC, block mapping technique and S.M.A.R.T to reduce invalidity or error. Once bad blocks are detected, data in those blocks will be transferred to free blocks and error will be corrected by designated algorithms.

#### 4.3 Wear Leveling

Flash memory devices differ from Hard Disk Drives (HDDs) in terms of how blocks are utilized. For HDDs, when a change is made to stored data, like erase or update, the controller mechanism on HDDs will perform overwrites on blocks. Unlike HDDs, flash blocks cannot be overwritten and each P/E cycle wears down the lifespan of blocks gradually. Repeatedly program/erase cycles performed on the same memory cells will eventually cause some blocks to age faster than others. This would bring flash storages to their end of service term sooner. Wear leveling is an important mechanism that level out the wearing of blocks so that the wearing-down of blocks can be almost evenly distributed. This will increase the lifespan of SSDs. Commonly used wear leveling types are Static and Dynamic.

## 4.4 Power Failure Management

Power Failure Management plays a crucial role when experiencing unstable power supply. Power disruption may occur when users are storing data into the SSD. In this urgent situation, the controller would run multiple write-to-flash cycles to store the metadata for later block rebuilding. This urgent operation requires about several milliseconds to get it done. At the next power up, the firmware will perform a status tracking to retrieve the mapping table and resume previously programmed NAND blocks to check if there is any incompleteness of transmission.

Note: The controller unit of this product model is designed with a DRAM as a write cache for improved performance and data efficiency. Though unlikely to happen in most cases, the data cached in the volatile DRAM might be potentially affected if a sudden power loss takes place before the cached data is flushed into non-volatile NAND flash memory.

#### 4.5 ATA Secure Erase

ATA Secure Erase is an ATA disk purging command currently embedded in most of the storage drives. Defined in ATA specifications, (ATA) Secure Erase is part of Security Feature Set that allows storage drives to erase all user data areas. The erase process usually runs on the firmware level as most of the ATA-based storage media currently in the market are built-in with this command. ATA Secure Erase can securely wipe out the user data in the drive and protects it from malicious attack.



#### **4.6 TRIM**

TRIM, though in capital letters usually, is a memory computation command rather than an abbreviation. It is mainly a SATA command that enables the operating system to inform the SSD (Solid State Drive) which blocks of previously stored data are no longer valid, due to erases by the host or operating system, such as file deletions or disk formatting. Once notified, SSD will begin the discard of the invalid LBAs and retain more space for itself, in fact, the discarded is no longer recoverable.

When an LBA is replaced by the operating system, as with overwrite of a file, the SSD is informed that the originally occupied LBA is determined as no longer in use or invalid. The SSD will not save those blocks in garbage collected sectors. Noticeably, a file deletion command by host or operating system never actually erases the actual content, rather, just the file is marked as deleted. This issue is even specifically noticeable for flash based memory devices, such as SSDs. In fact, an SSD will keep garbage collecting the invalid, previously occupied LBAs, if it is not informed that these LBAs can be erased. Thus, the SSD would experience a significant performance downfall.

### 4.7 SATA Power Management

By complying with SATA 6.0 Gb/s specifications, the SSD supports the following SATA power saving modes:

- ACTIVE: PHY ready, full power, Tx & Rx operational
- PARTIAL: Reduces power, resumes in under 10 µs (microseconds)
- SLUMBER: Reduces power, resumes in under 10 ms (milliseconds)
- HIPM: Host-Initiated Power Management
- DIPM: Device-Initiated Power Management
- Device Sleep (DevSleep or DEVSLP): PHY powered down; power consumption  $\leq$  5 mW; host assertion time  $\leq$  10 ms; exit timeout from this state  $\leq$  20 ms (unless specified otherwise in SATA Identify Device Log).

#### Note:

- 1. The behaviors of power management features would depend on host/device settings.
- 2. Device Sleep mode is optional, depending on product ordering selections.



## 5. Software Interface

#### 5.1 Command Set

This section defines the software requirements and the format of the commands the host sends to P201-M. Commands are issued to P201-M by loading the required registers in the command block with the supplied parameters, and then writing the command code to the Command register.

Table 6-1: Command set

Command	Code	Command	Code
Data Set Management	06h	CHECK POWER MODE	98h
Recalibrate	10h-1Fh	SLEEP	99h
Read Sectors	20h	SMART	B0h
Read Sectors without Retry	21h	DEVICE CONFIGURATION	B1h
Read Sectors EXT	24h	Read Multiple	C4h
Read DMA EXT	25h	Write Multiple	C5h
Read Native Max Address EXT	27h	Set Multiple Mode	C6h
Read Multiple EXT	29h	Read DMA	C8h
Read Log EXT	2Fh	Read DMA without Retry	C9h
Write Sectors	30h	Write DMA	CAh
Write Sectors without Retry	31h	Write DMA without Retry	CBh
Write Sectors EXT	34h	Write Multiple FUA EXT	CEh
Write DMA EXT	35h	Standby Immediate	E0h
Set Native Max Address EXT	37h	Idle Immediate	E1h
CFA WRITE SECTORS WITHOUT ERASE	38h	Standby	E2h
Write Multiple EXT	39h	IDLE	E3h
Write DMA FUA EXT	3Dh	Read Buffer	E4h
Write Long EXT	3Fh	Check Power Mode	E5h
Read Verify Sectors	40h	Sleep	E6h
Read Verify Sectors without Retry	41h	Flush Cache	E7h
Read Verify Sectors EXT	42h	Write Buffer	E8h
WRITE UNCORRECTABLE EXT	45h	Flush Cache EXT	EAh
Read FPDMA Queued	60h	Identify Device	ECh
Write FPDMA Queued	61h	Set Features	EFh
Seek	70h-71h	Security Set Password	F1h
Execute Device Diagnostic	90h	Security Unlock	F2h
Initialize Device Parameters	91h	Security Erase Prepare	F3h
Download Microcode	92h	Security Erase Unit	F4h



DOWNLOAD MICROCODE DMA	93h	Security Freeze Lock	F5h
STANDBY IMMEDIATE	94h	Security Disable Password	F6h
IDLE IMMEDIATE	95h	Read Native Max Address	F8
STANDBY	96h	Set Max Address	F9
IDLE	97h		

#### 5.2 S.M.A.R.T.

SMART, an acronym for Self-Monitoring, Analysis and Reporting Technology, is an open standard that allows a hard disk drive to automatically detect its health and report potential failures. When a failure is recorded by SMART, users can choose to replace the drive to prevent unexpected outage or data loss. Moreover, SMART can inform users of impending failures while there is still time to perform proactive actions, such as copy data to another device



# **6. Electrical Specification**

Table 6-1: Operating range

Ambient Temperature	0°C to +70°C
Supply Voltage	3.3V±5% (3.135-3.465V)

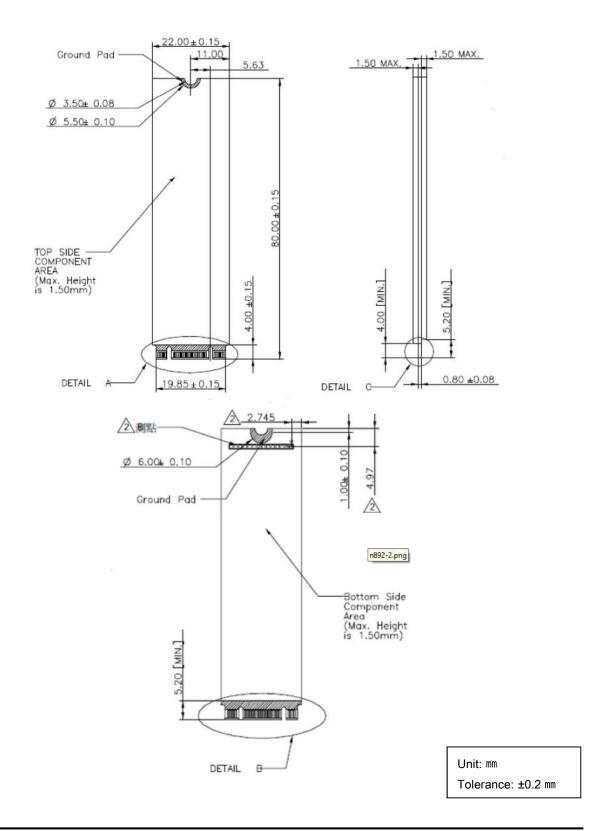
Table 6-2: Typical power consumption

Capacity	16 GB	32 GB	64 GB	128 GB	256 GB
Active (mA)	355	470	445	535	600
Idle (mA)	85	85	90	90	90

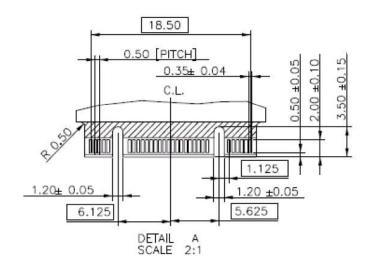
Note: Results may differ from various flash configurations or host system setting

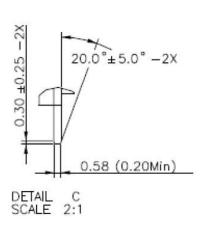


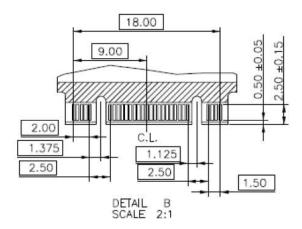
# 7. Physical Characteristics











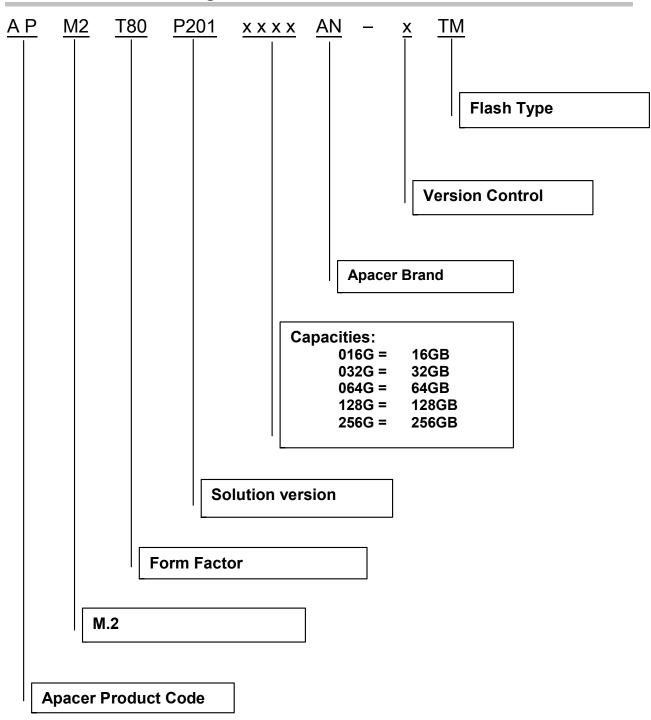
Unit: mm

Tolerance: ±0.2 mm



# **8. Product Ordering Information**

## 8.1 Product Code Designations





## **8.2 Valid Combinations**

Capacity	No DEVSLP	DEVSLP
16GB	APM2T80P201016GAN-1TM	APM2T80P201016GAN-2TM
32GB	APM2T80P201032GAN-1TM	APM2T80P201032GAN-2TM
64GB	APM2T80P201064GAN-1TM	APM2T80P201064GAN-2TM
128GB	APM2T80P201128GAN-1TM	APM2T80P201128GAN-2TM
256GB	APM2T80P201256GAN-1TM	APM2T80P201256GAN-2TM

**Note:** Valid combinations are those products in mass production or will be in mass production. Consult your Apacer sales representative to confirm availability of valid combinations and to determine availability of new combinations.



# **Revision History**

Revision	Date	Description	Remark
1.0	10/28/2014	Official release	
1.1	12/23/2014	Updated power consumption specification	



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